



UNIVERSITY OF
BIRMINGHAM

GRAVITATIONAL
WAVE ASTRONOMY

LECTURE 2: GRAVITATIONAL-WAVE DATA ANALYSIS FOR COMPACT BINARIES

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ISCRA 2024



SUMMARY LECTURE 1

- ▶ Gravitational waves are propagating oscillations of a gravitational field **generated by accelerating masses**
 - ▶ They **change the proper separation** between freely-falling test bodies
 - ▶ GWs **carry energy & momentum** from the source
- ▶ Spacetime is stiff - "extreme" events are needed to produce a measurable strain
 - ▶ **Compact binary mergers, CCSNe, rotating neutron stars, stochastic GW background**
- ▶ Operating GW detectors are km-scale (sophisticated) **Michelson interferometers**
 - ▶ The **sensitivity** is characterised by the **noise power spectral density (PSD)**
 - ▶ Current generation of GW detectors can measure length changes $\delta L \simeq 10^{-18}m$
 - ▶ Observe GWs with frequencies between 20-2000 Hz



DATA ANALYSIS FOR COMPACT BINARIES

GW detection

Parameter estimation

Modelling gravitational waves

(Some) Recommended literature:

★ Luc Blanchet, Living Reviews in Relativity: <https://link.springer.com/article/10.12942/lrr-2014-2>

★ Buonanno & Sathyaprakash: <https://arxiv.org/abs/1410.7832>

★ Talbot & Thrane: <https://arxiv.org/abs/1809.02293>



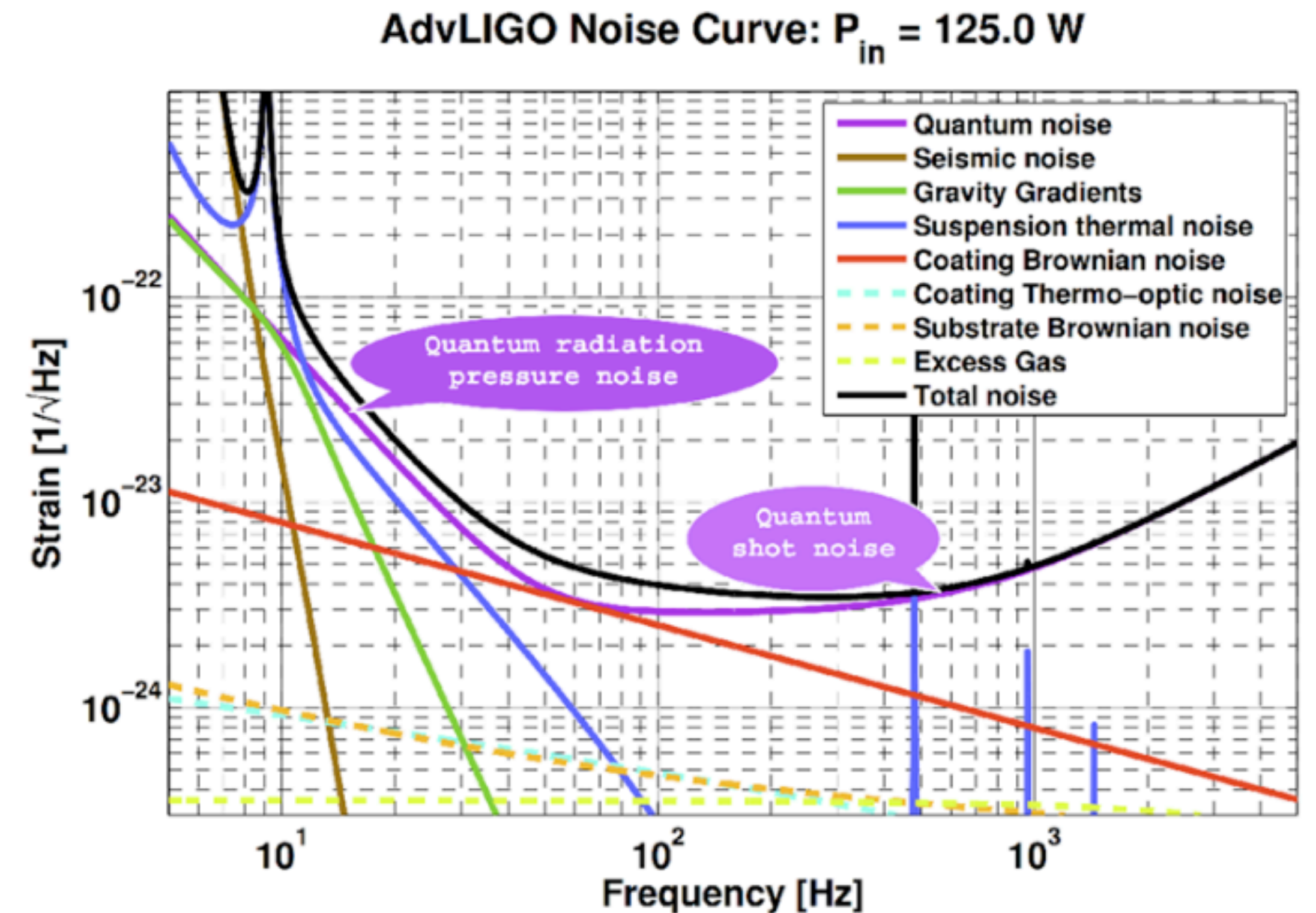
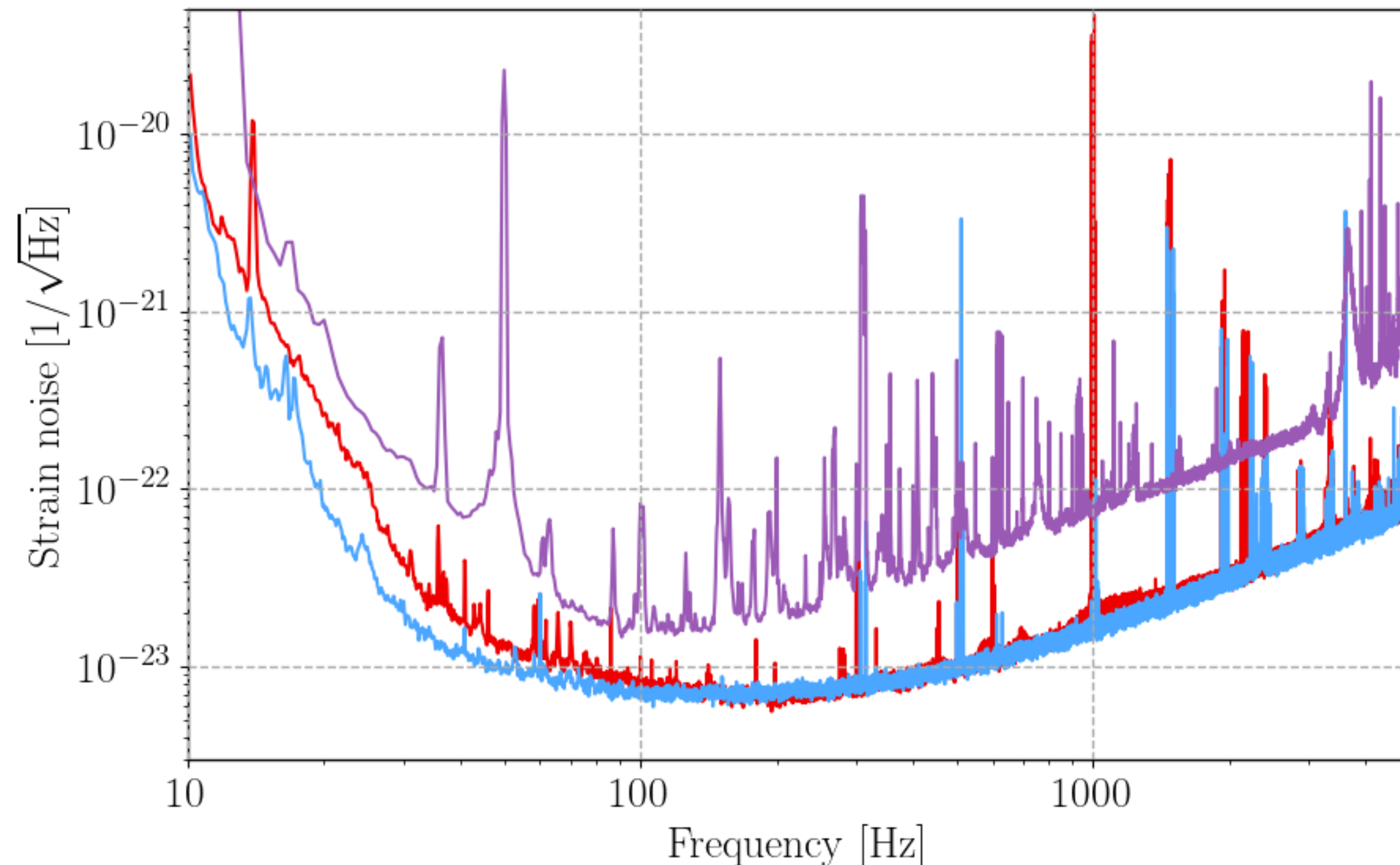
SENSITIVITY

- ▶ The sensitivity of GW detector is characterised by the **power spectral density (PSD)** of its noise background in the absence of a GW signal.

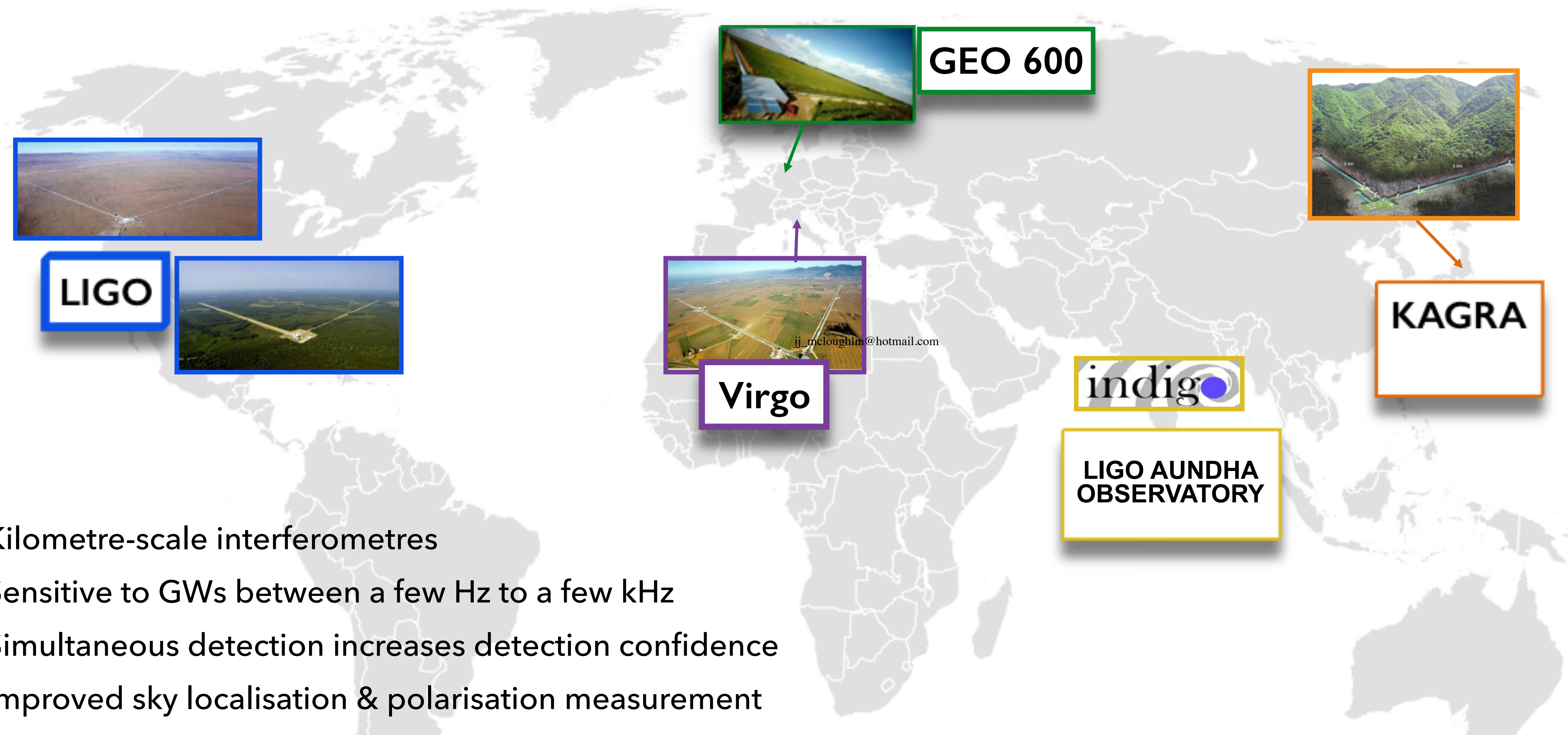
- ▶ $S_n(f)$ is the **noise power spectral density** - the Fourier transform of the noise autocorrelation function: $\langle \tilde{n}(f)\tilde{n}^*(f') \rangle = \frac{1}{2}S_n(f)\delta(f - f')$

Assuming stationary & Gaussian

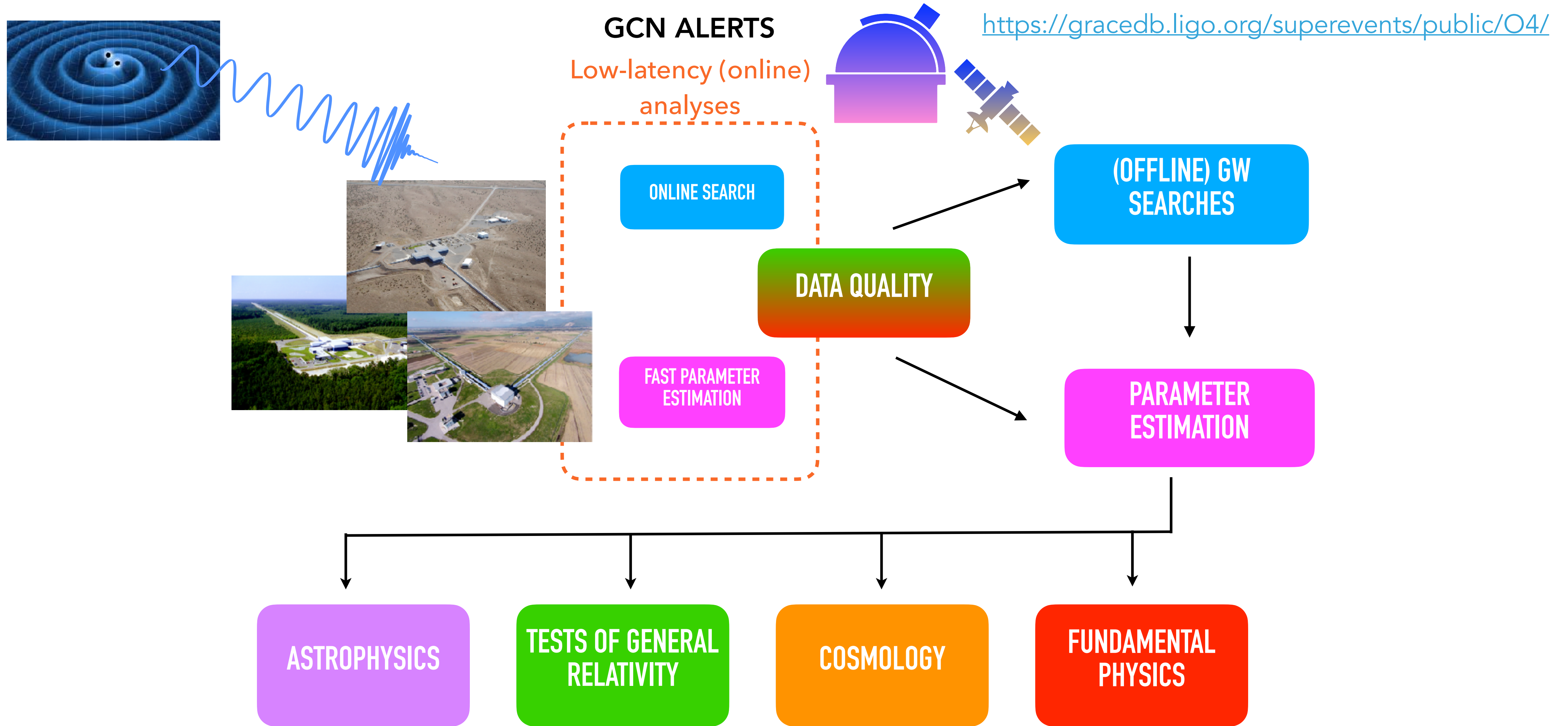
Amplitude spectral density = $\sqrt{\text{PSD}}$



DETECTOR NETWORK



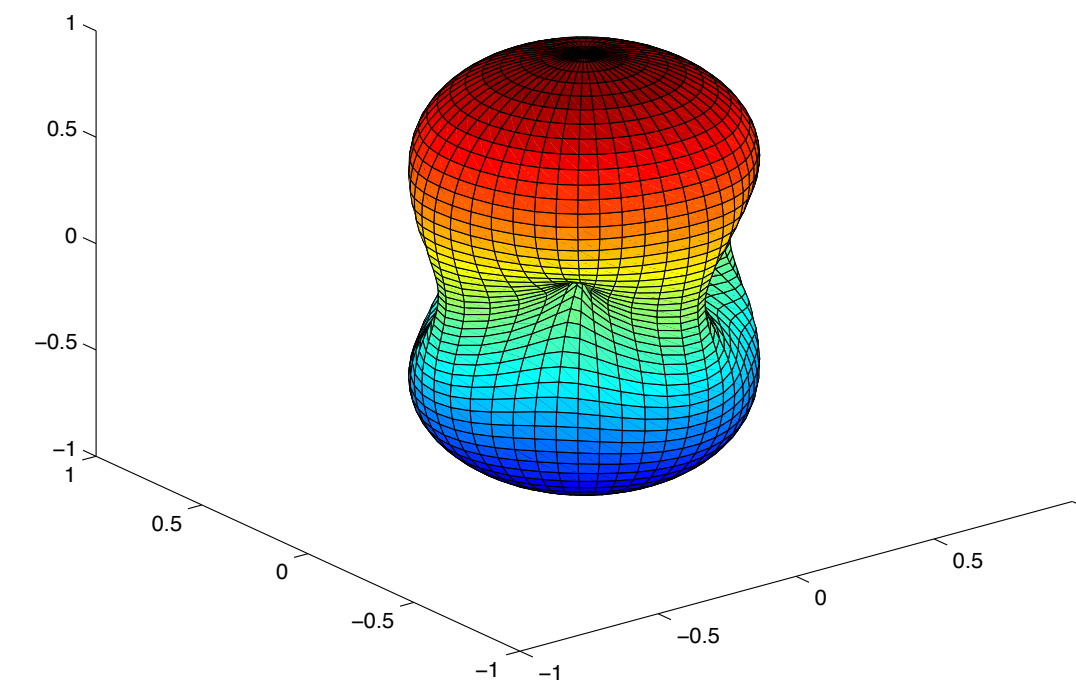
- ▶ Kilometre-scale interferometres
- ▶ Sensitive to GWs between a few Hz to a few kHz
- ▶ Simultaneous detection increases detection confidence
- ▶ Improved sky localisation & polarisation measurement
- ▶ Increased duty cycle



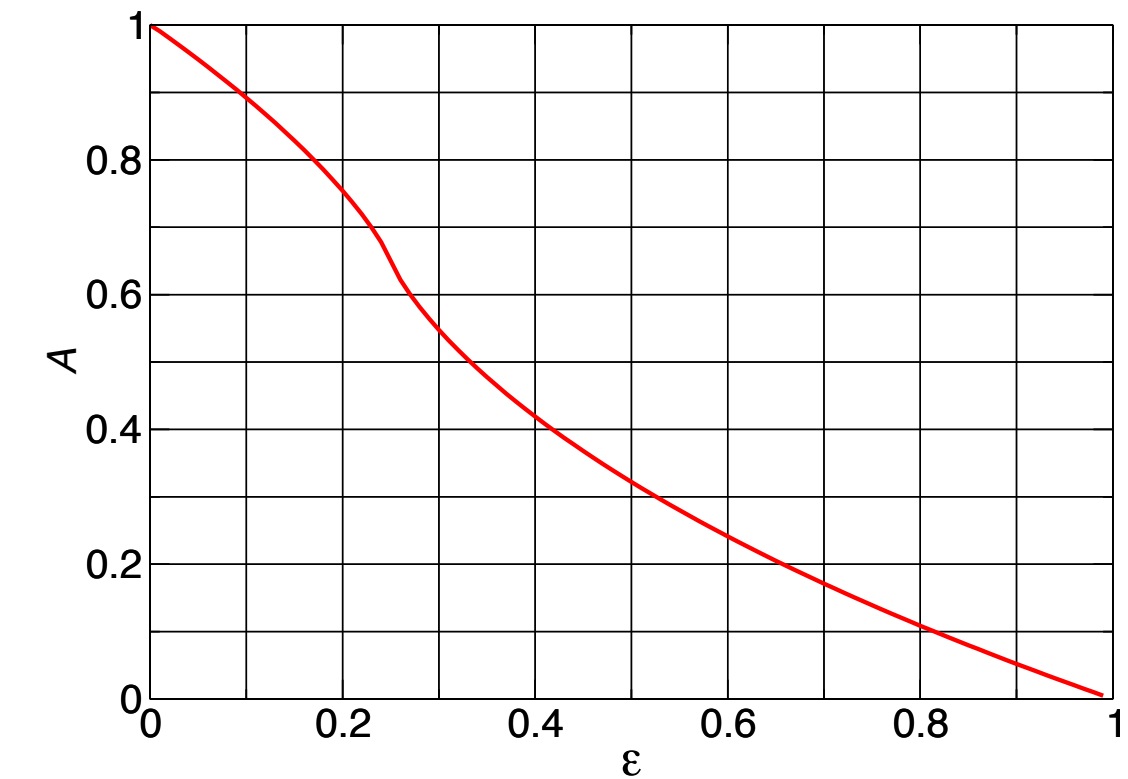
LOCALISATION

- ▶ Individual GW detectors are omnidirectional: poor localisation! Sensitivity depends on location, polarisation and frequency
- ▶ Simultaneously operating observatories allow for triangulation via arrival time differences

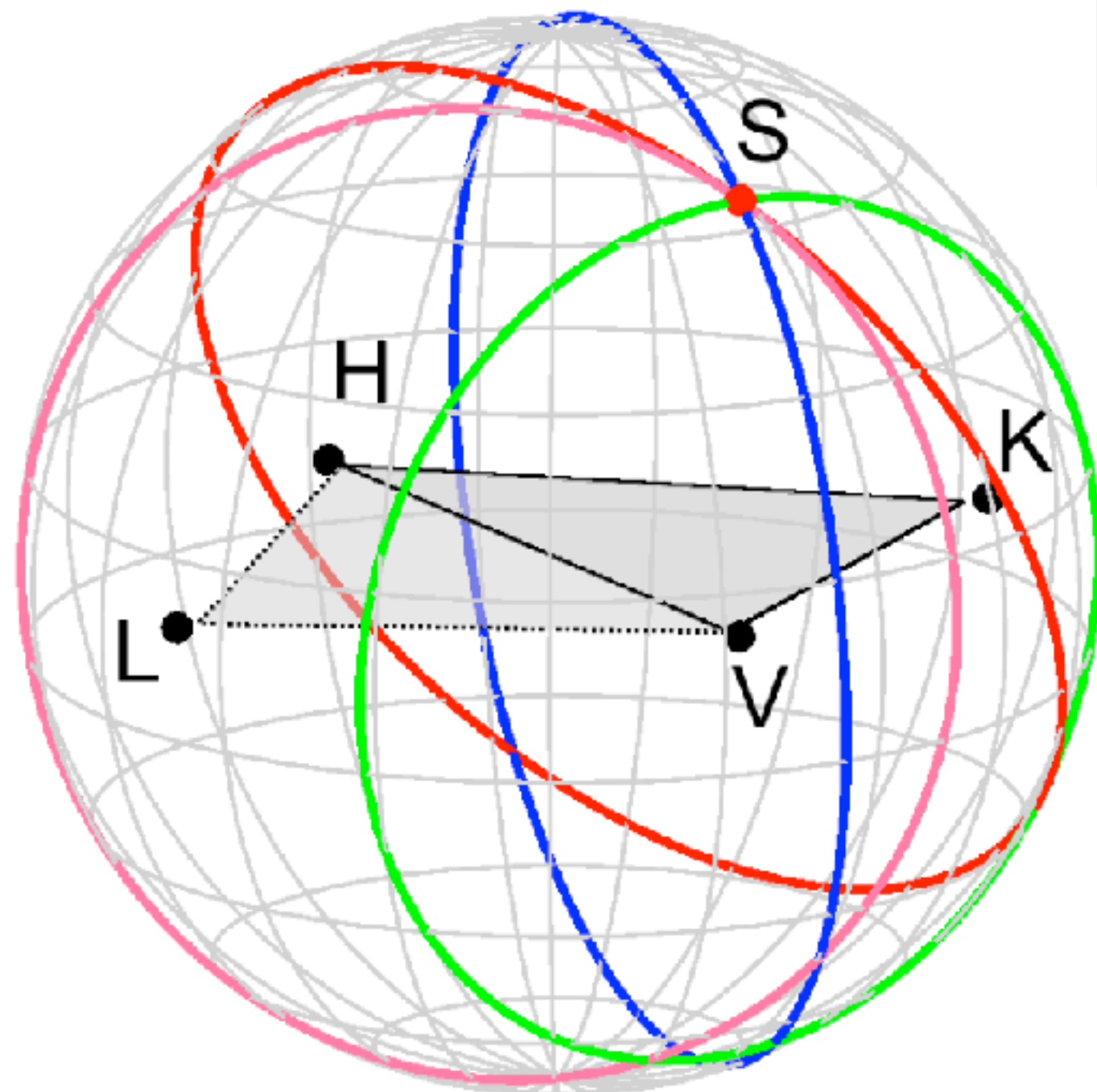
RMS antenna response



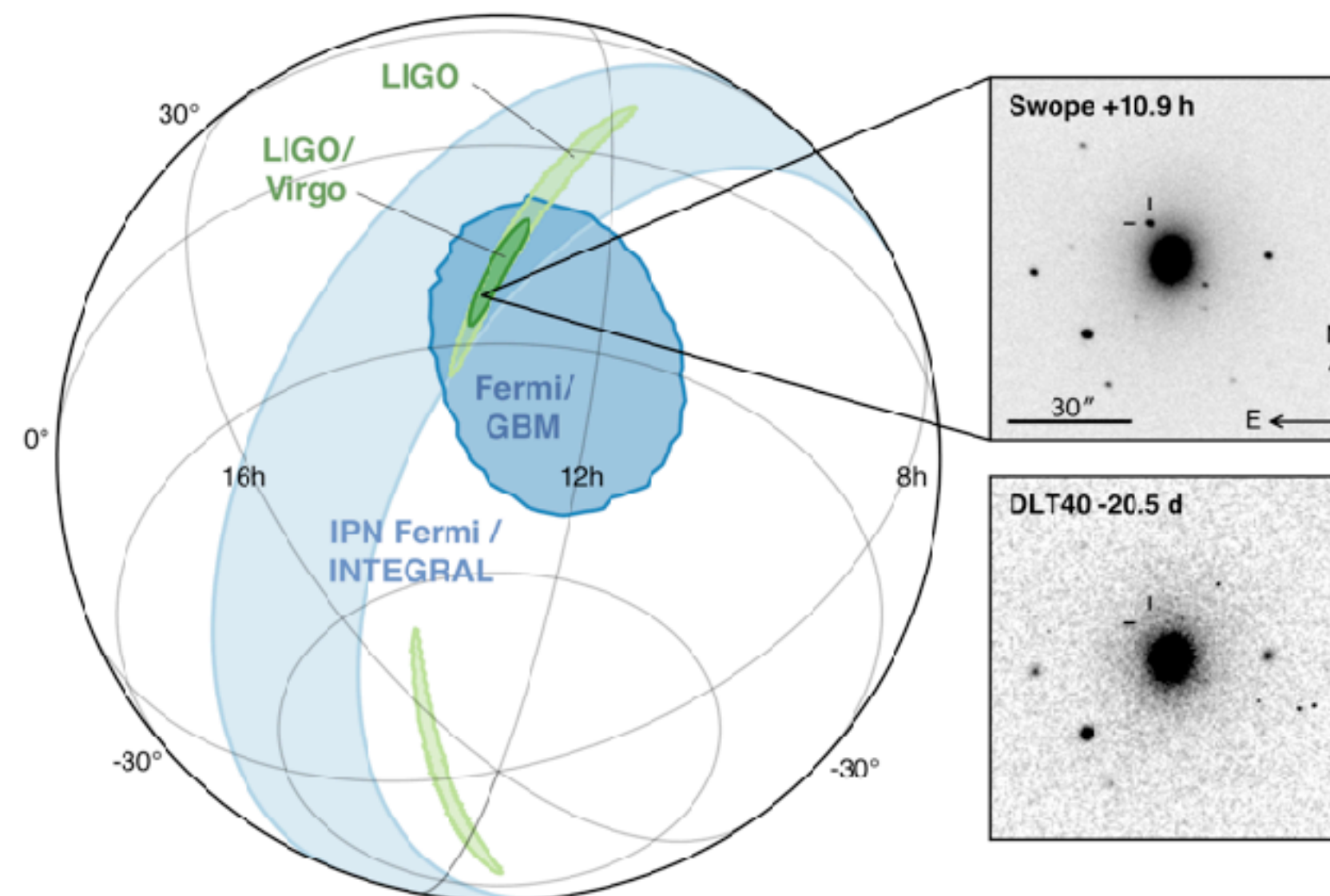
[Sathyaprakash&Schutz, LRR]



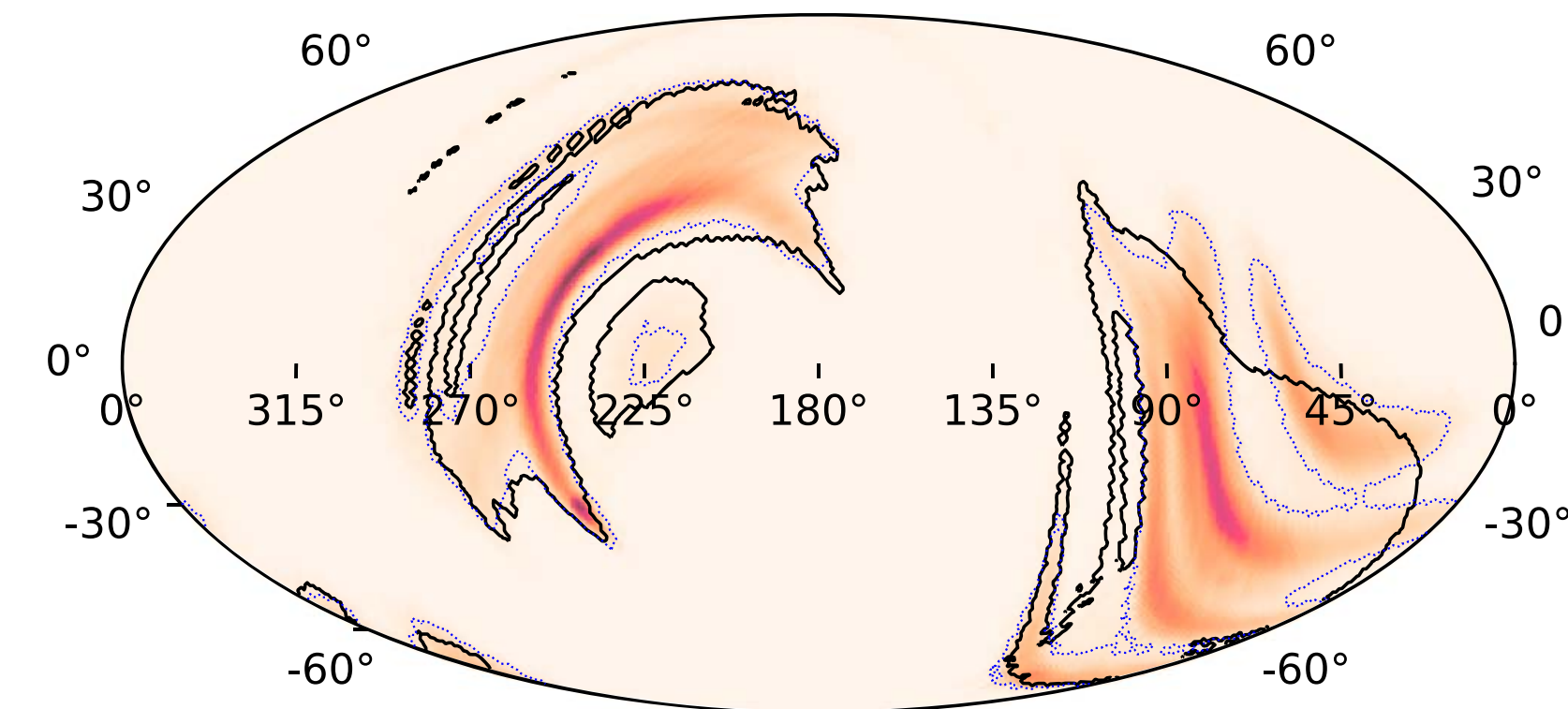
- HL
- HV
- LK
- KV



GW170817



GW190425



90% CI ~ 8300 deg²

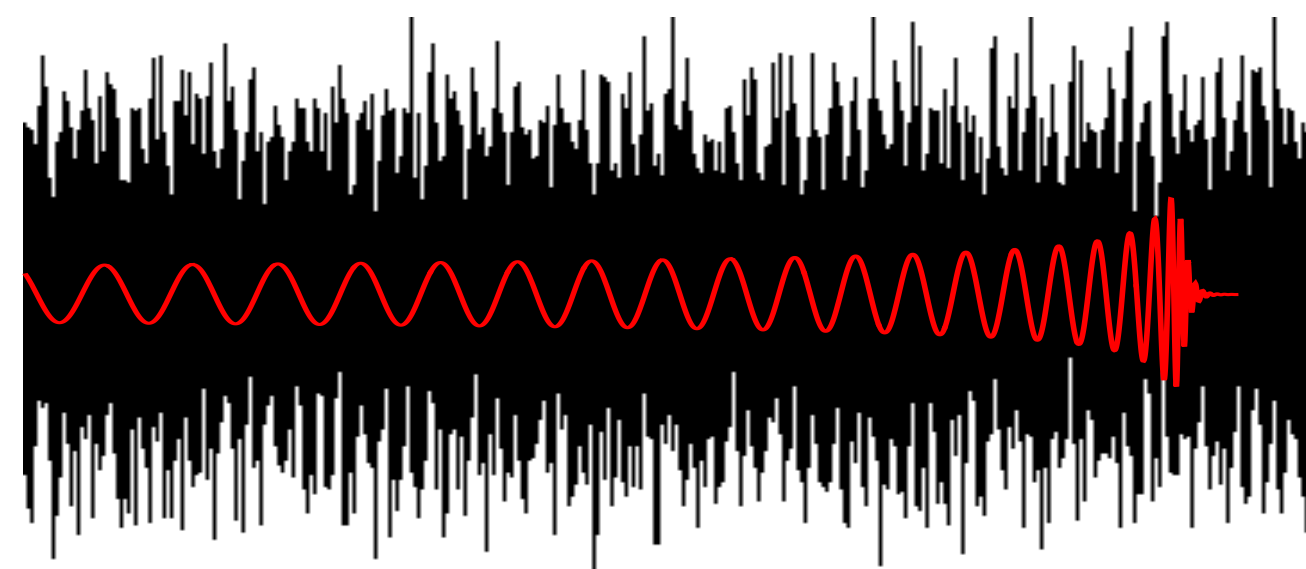
[LVK Observing Scenarios & LVK discovery papers]



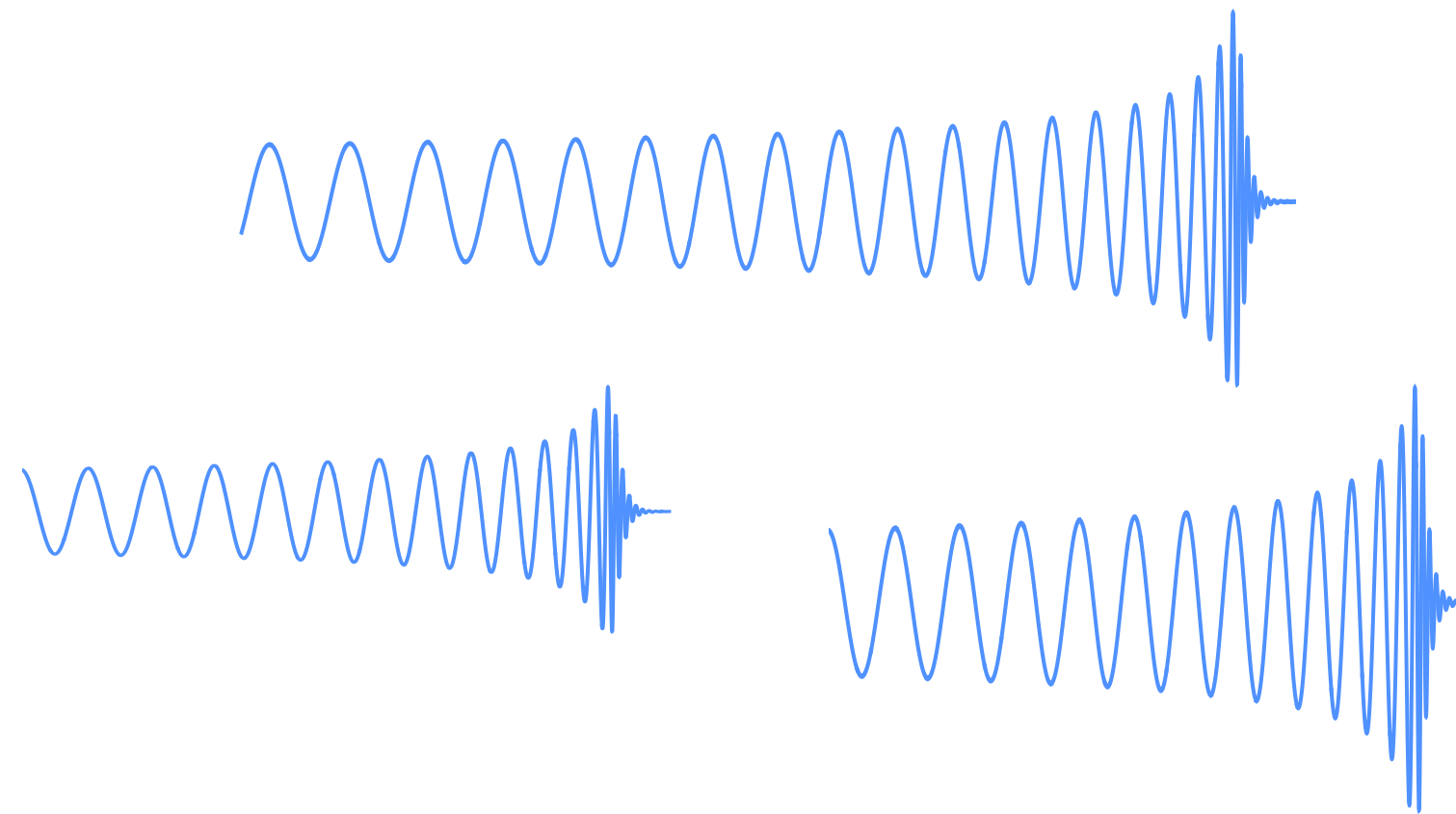
MODELLED SEARCHES

- ▶ Optimal detection strategy for a **modelled signal** in stationary Gaussian noise = **matched filtering**

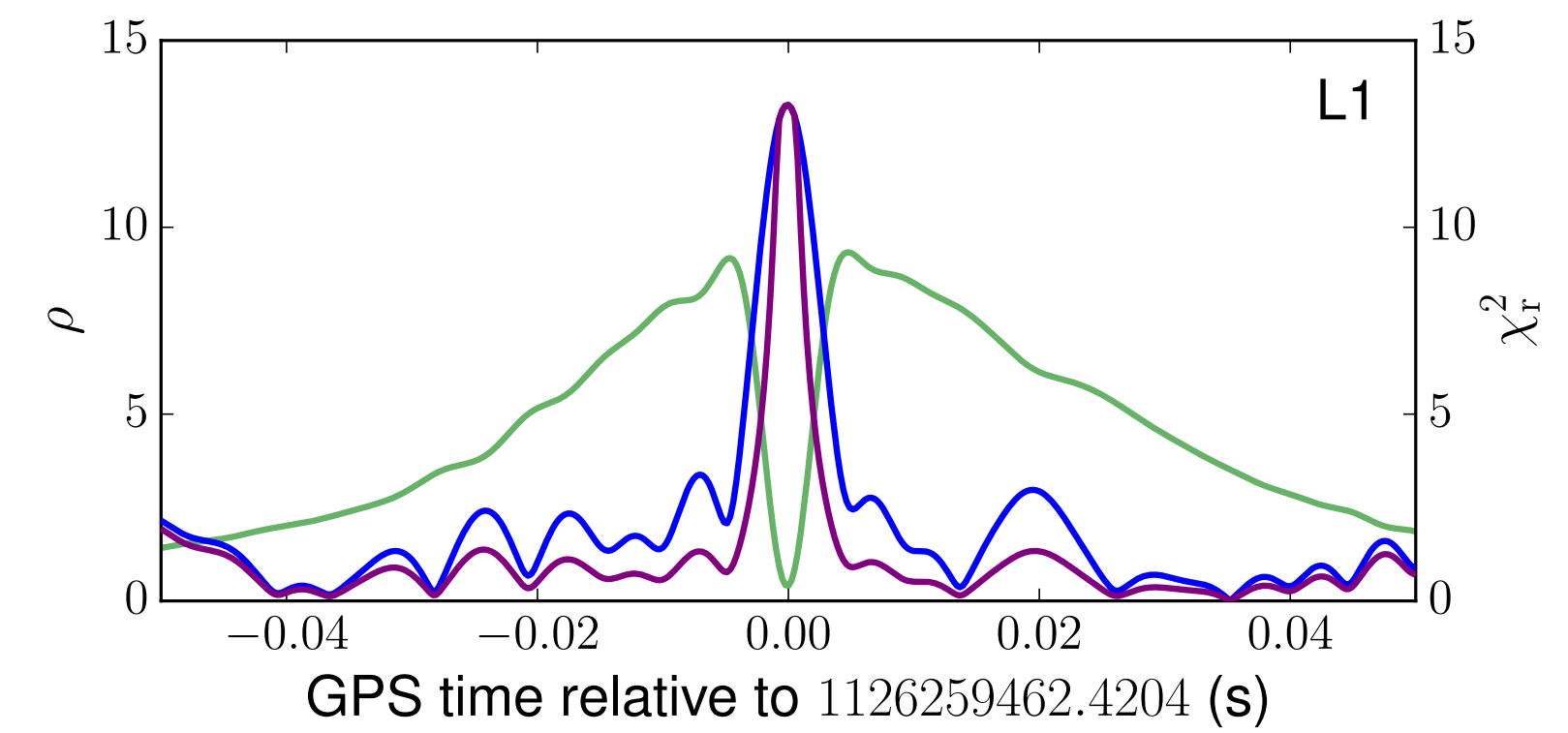
strain data d



template waveforms h



SNR time series



▶ **Optimal filter:** $\rho = \frac{\langle d|h \rangle}{\sqrt{\langle h|h \rangle}}$

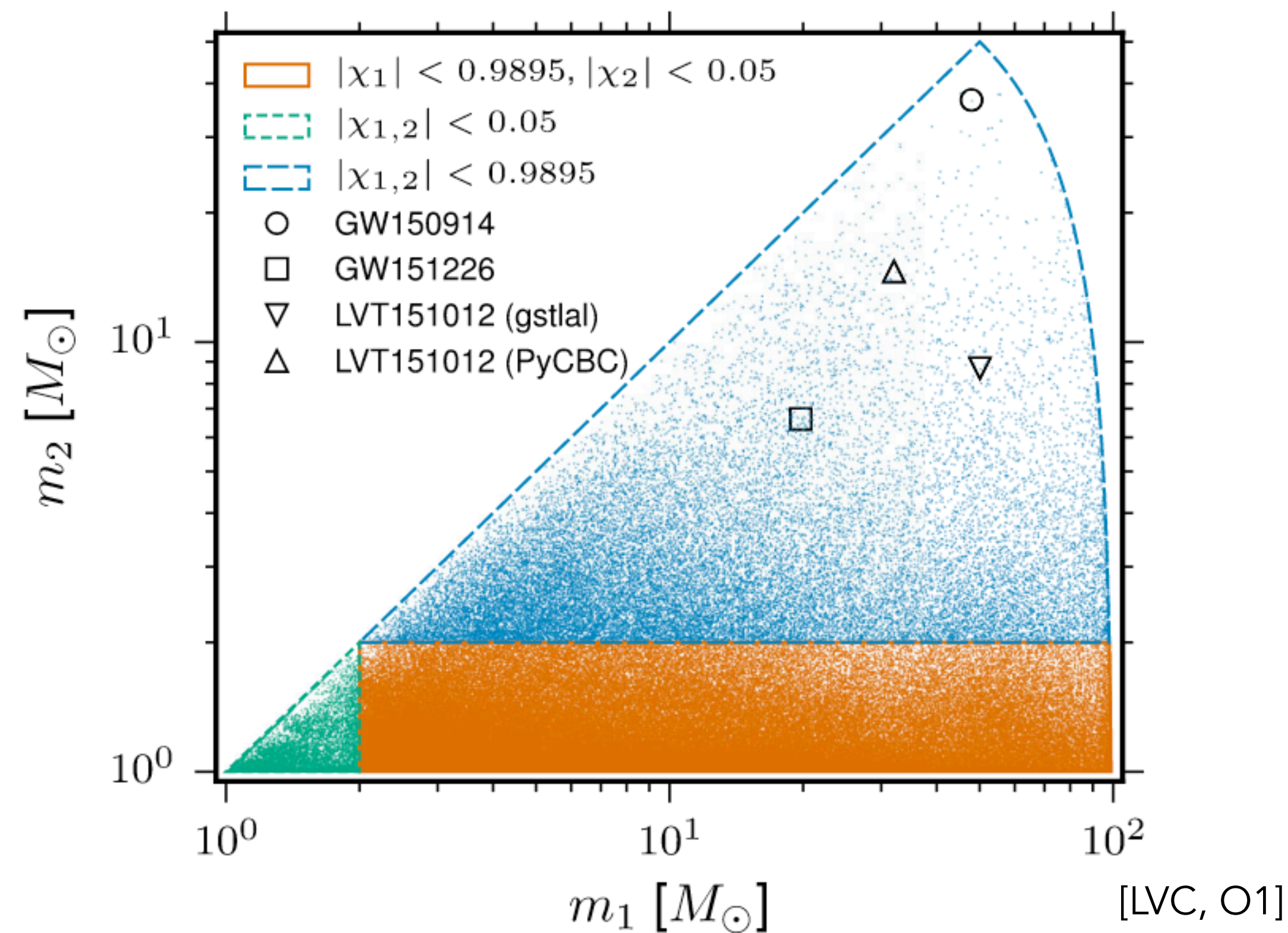
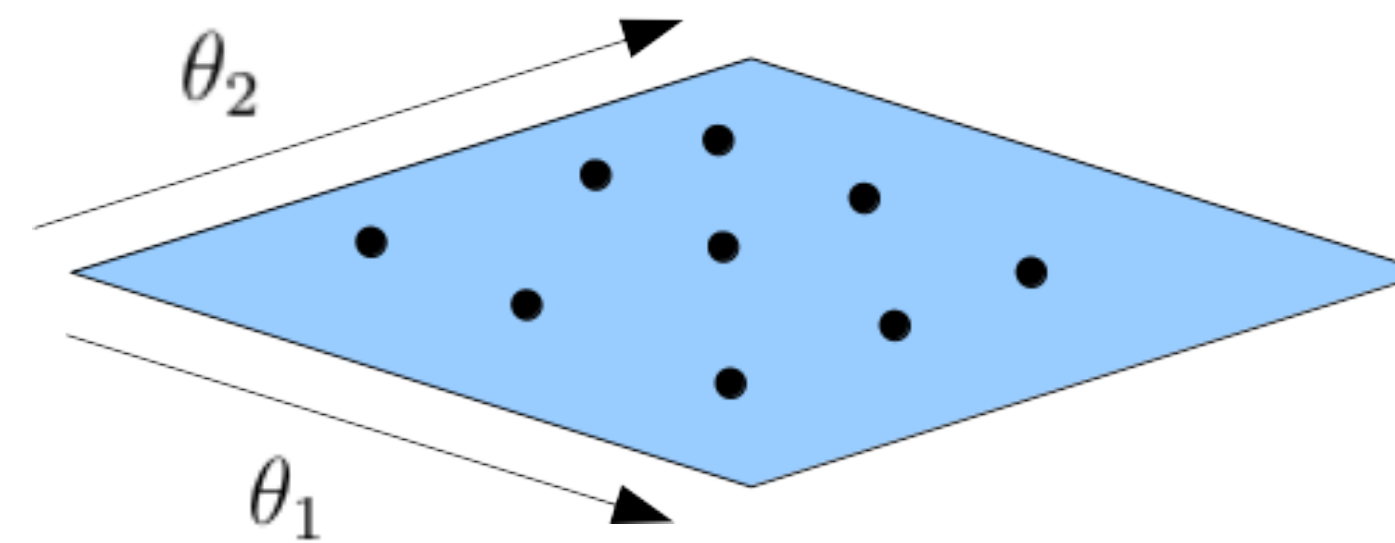
$$\langle a|b \rangle = 4 \int_0^\infty df \frac{\tilde{a}(f)\tilde{b}^*(f)}{S_n(f)}$$

signal-to-noise ratio (SNR)



TEMPLATE BANKS

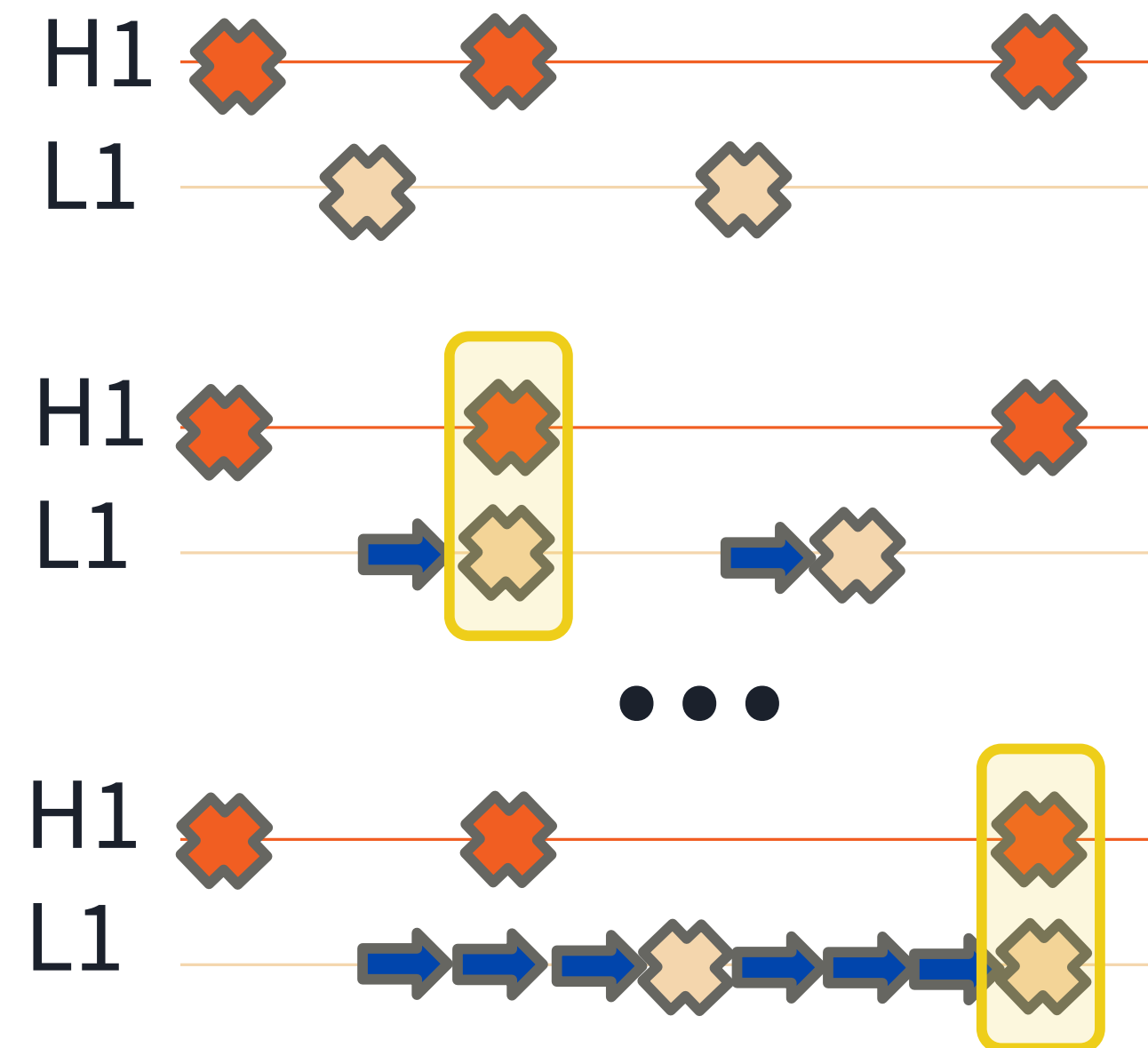
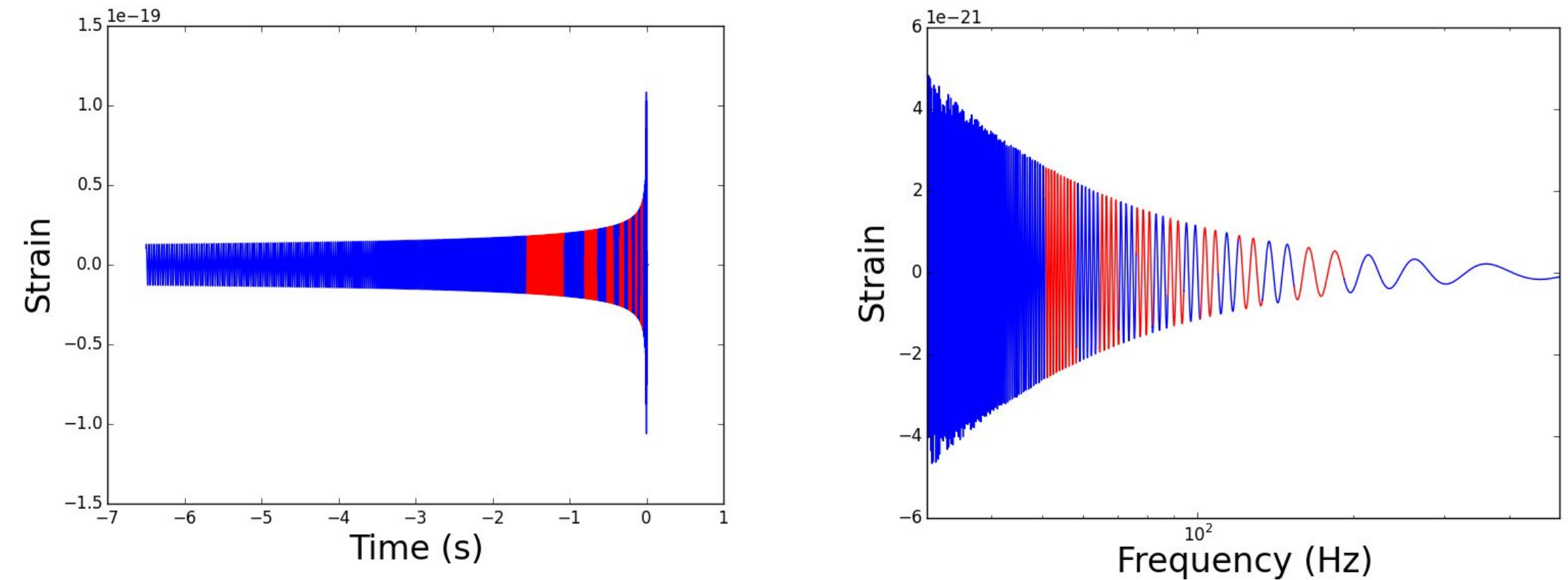
- ▶ Large collection of theoretical waveform templates:
- ▶ Construction: hybrid method
 - ▶ Geometric lattice for known metric (green area)
 - ▶ Metric = mismatch between neighbouring templates $1 - \langle \hat{h}(\theta) | \hat{h}(\theta + \Delta\theta) \rangle = g_{ij} \Delta\theta_i \Delta\theta_j$
 - ▶ Stochastic placement
- ▶ What's included?
 - ▶ Component masses
 - ▶ Aligned-spins
 - ▶ Quadrupolar mode



EVENT SELECTION

- ▶ Apply any data excursions
- ▶ Filter each data stream individually
- ▶ Apply threshold SNR cut and cluster to generate triggers
- ▶ Perform χ^2 -test to check signal consistency
- ▶ Check time & parameter coincidence between different IFOs
- ▶ Apply data quality vetoes
- ▶ Surviving triggers form GW candidates
- ▶ Use **time shifts** to calculate the **false-alarm-rate (FAR)** of coincident triggers. Resulting triggers form the background, which is used to determine the significance of the foreground candidates.

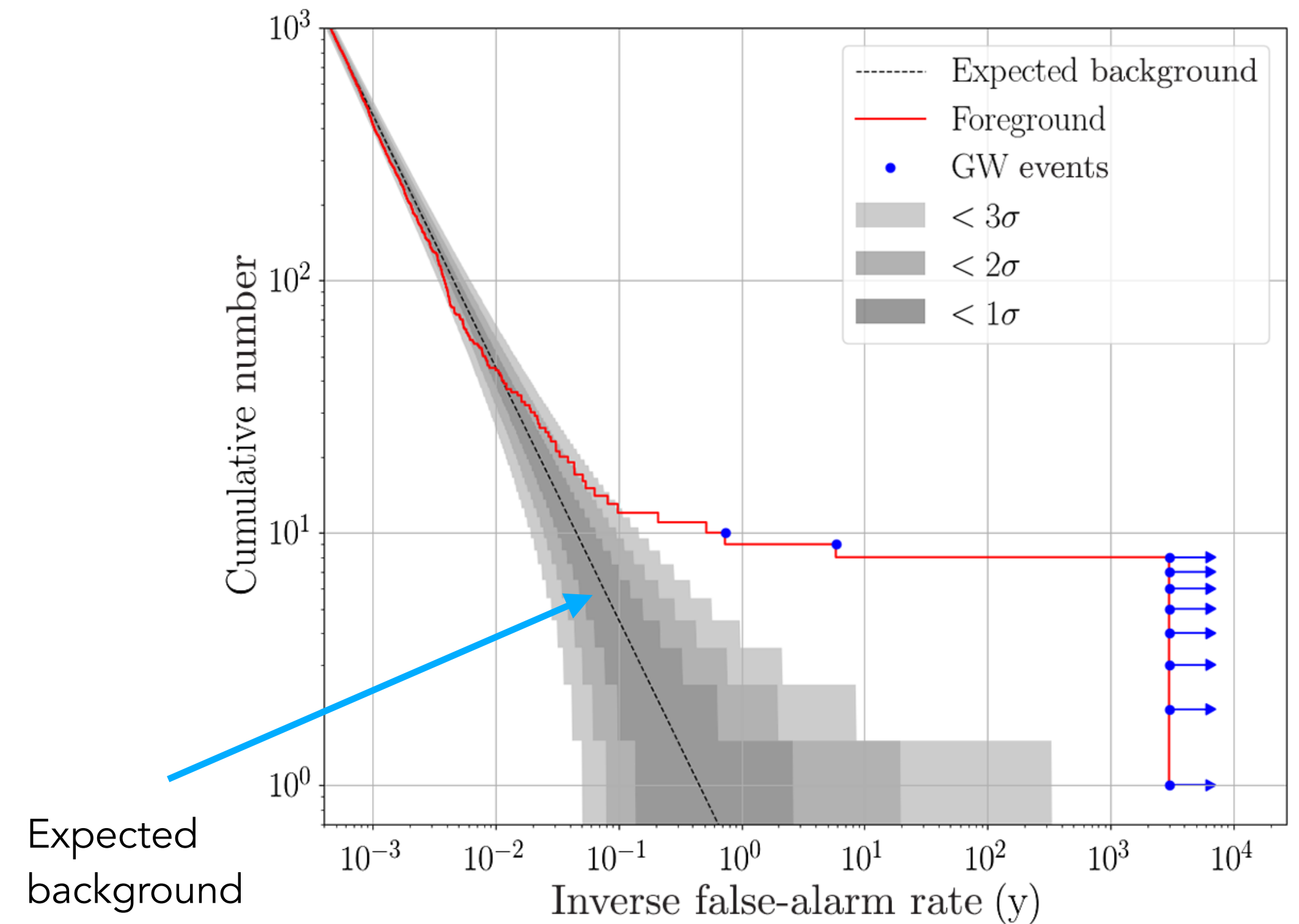
Example: SNR accumulation as signal-consistency test



SIGNIFICANCE

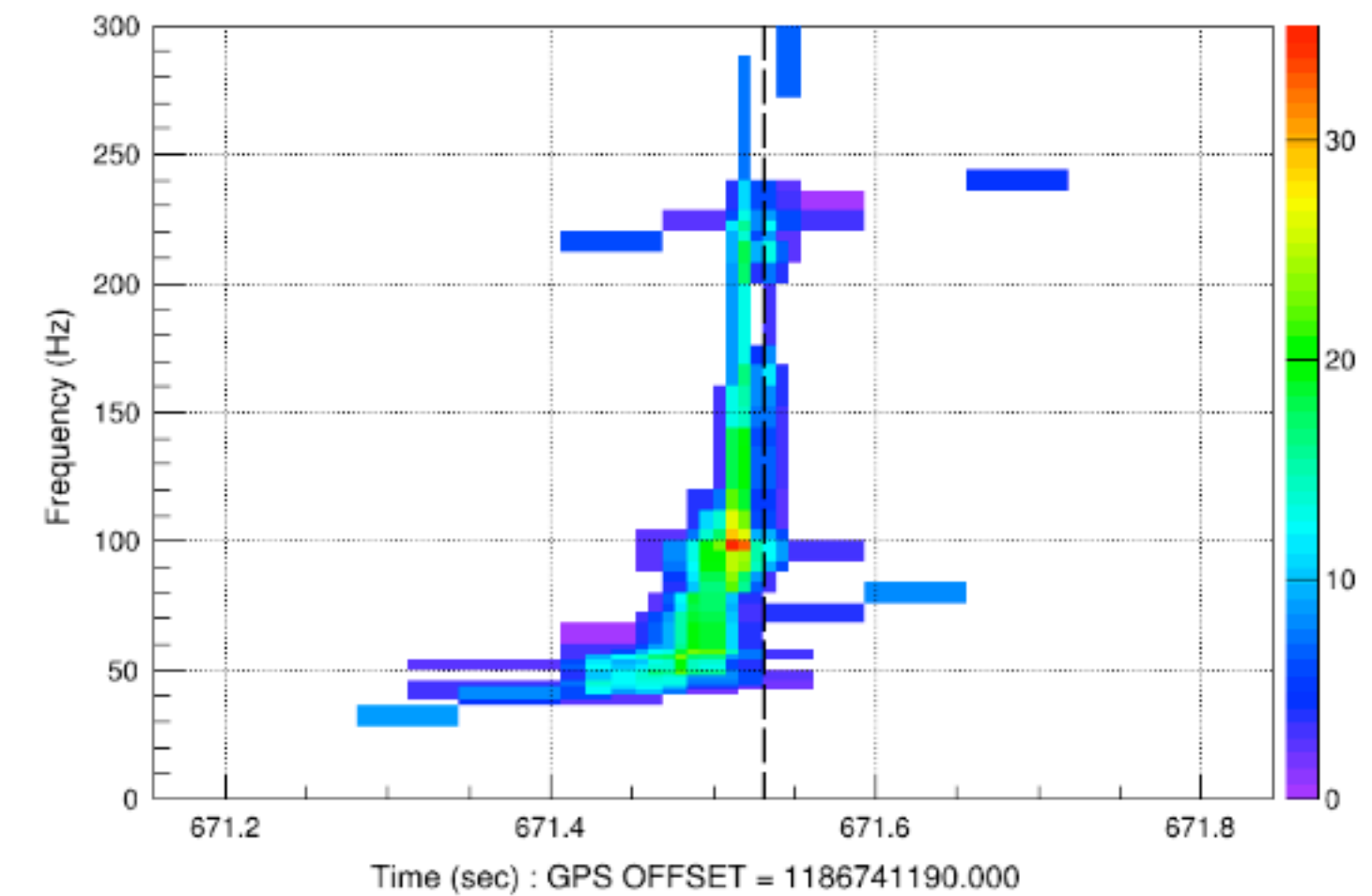
- ▶ **FAR** (caution: varies!): e.g. O2 1/30 days (expect ~2 false alarms per month)

- ▶ **Astrophysical probability**: assumes 4 categories A_i (terrestrial, BBH, BNS, NSBH) each described by a Poisson process (inhomogeneous Poisson mixture model) with mean Λ_i [Farr+, 2013]
 - ▶ Ranking statistic distribution: $p(x | A_i, \{\theta\})$
 - ▶ $\Lambda_i = \langle VT \rangle_{\{\theta\}} \times R_i$
 - ▶ Observable spacetime volume (selection effects!)
 - ▶ Models are marginalised over the counts with the ranking statistic distribution fixed at the value of the ranking statistic of the candidate

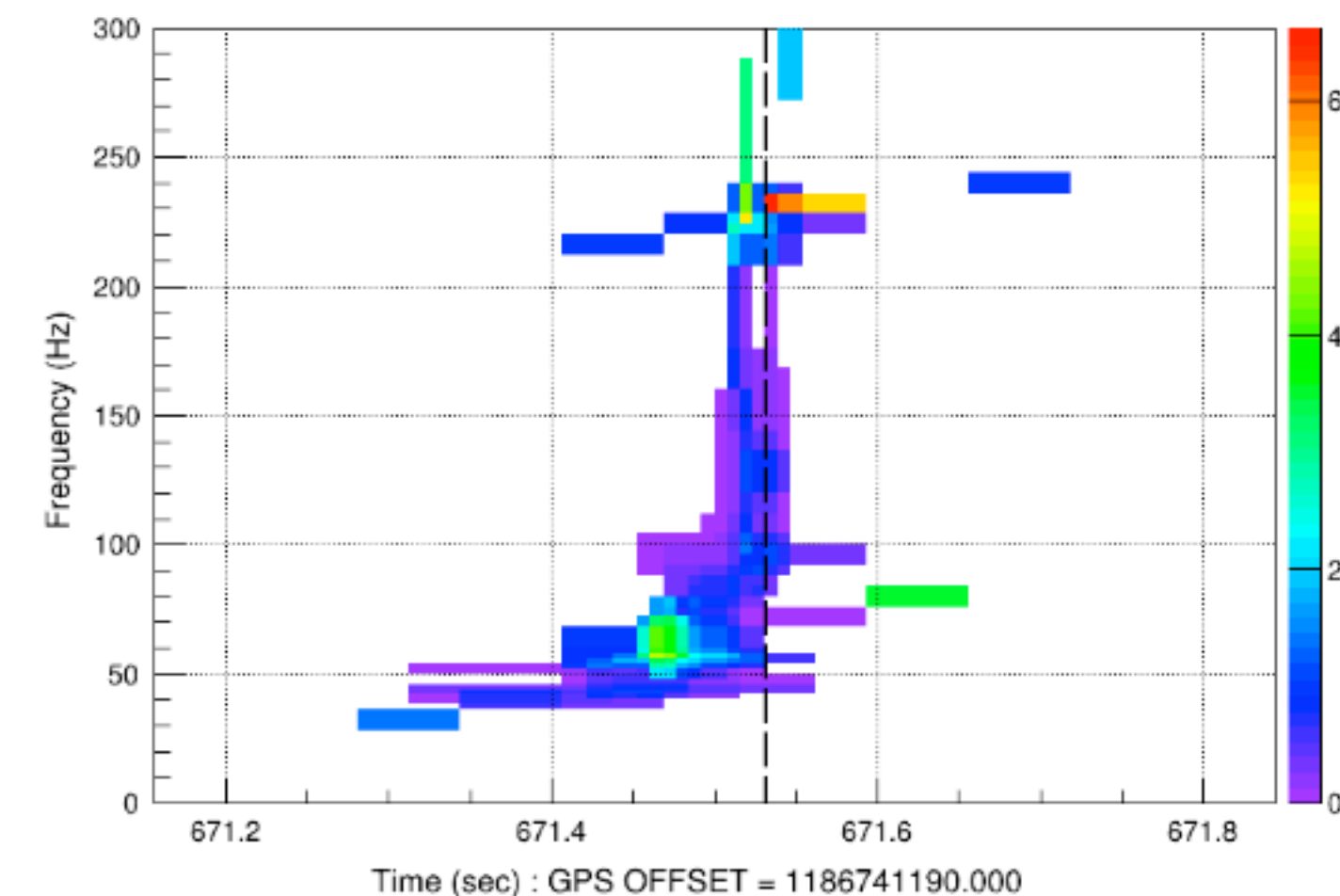


UNMODELLED SEARCHES

- ▶ Search that identifies **coincident excess power** in the time-frequency representation of the strain data
- ▶ Identifies events that are coherent in multiple detectors and reconstructs the source sky location and signal waveforms by using the constrained maximum likelihood method
- ▶ Does not rely on waveform models
- ▶ Sensitive to a wide range of short-duration transient signals ("bursts")
- ▶ Weak assumption of "chirpyness" of the signal
- ▶ Detection statistic: coherent energy constructed via cross-correlation $E_c \propto \rho_c$



(c)

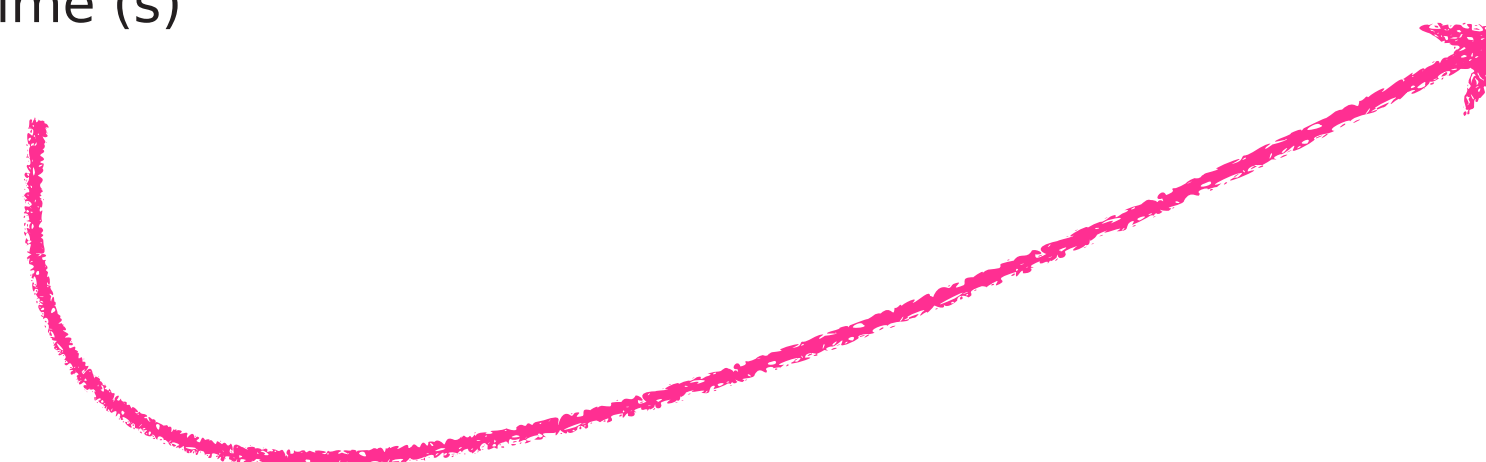
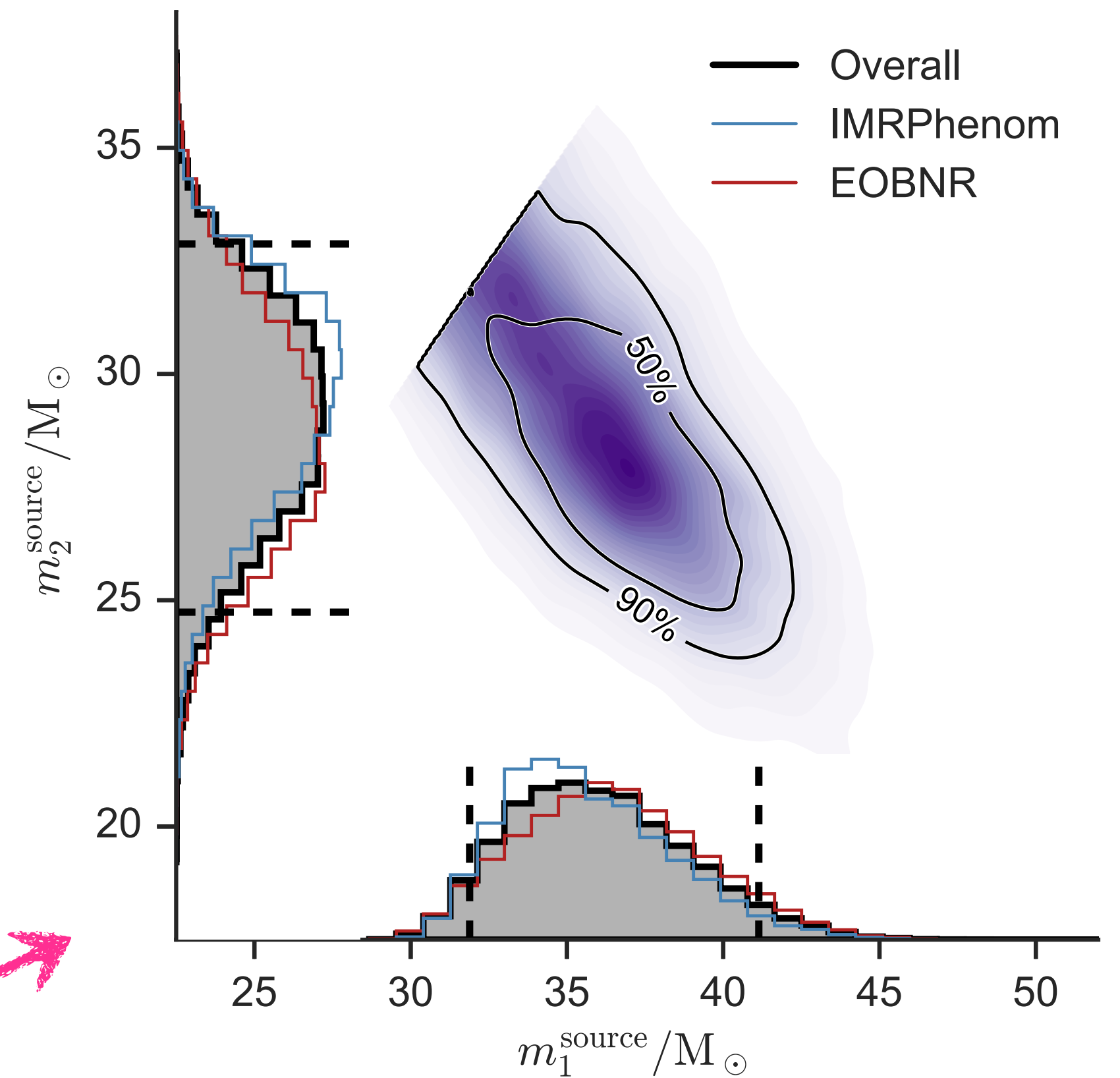
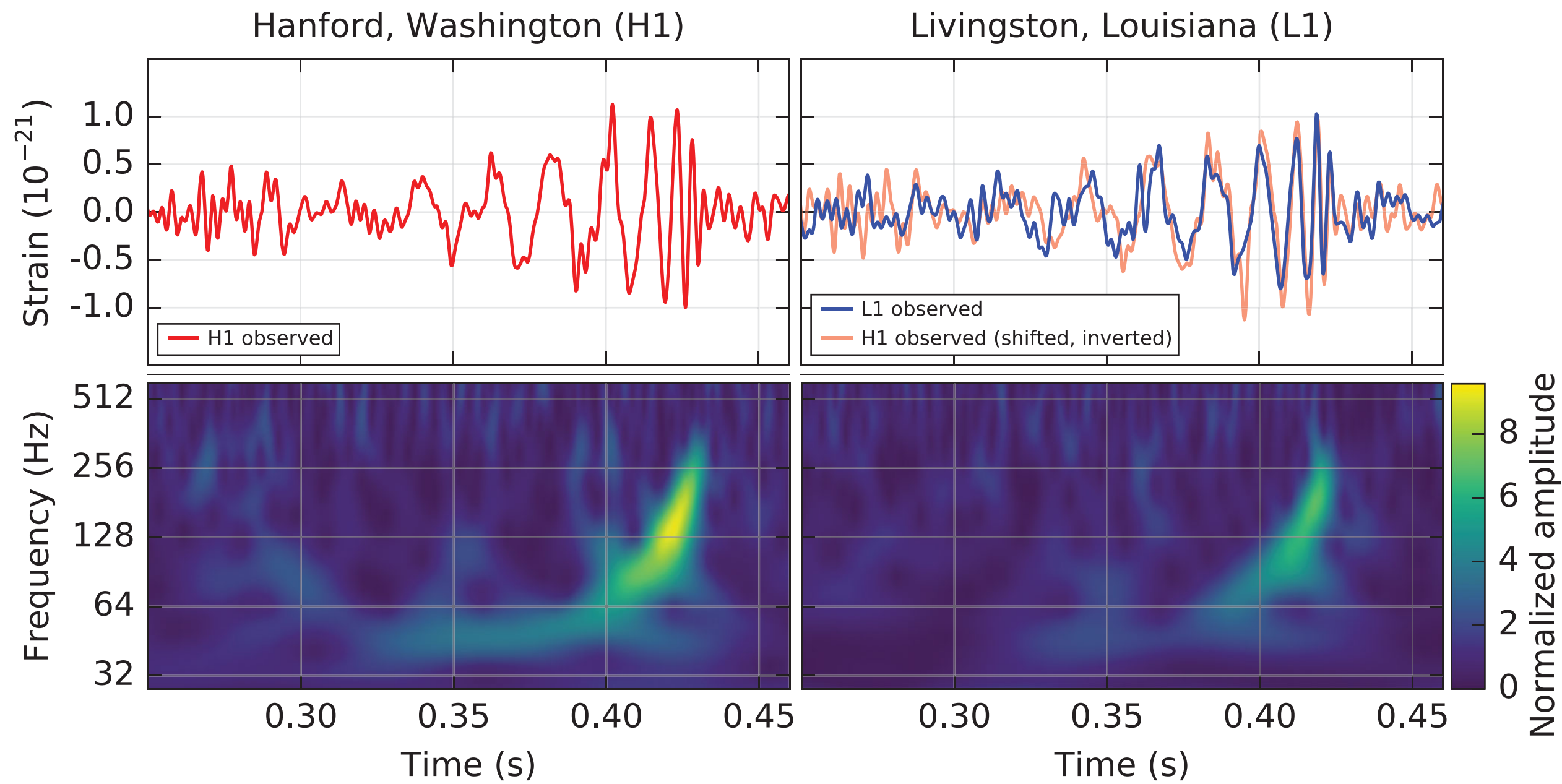


SOURCE CHARACTERISATION

Calibrated (raw-ish) strain data



Astrophysical parameter distributions



[LVC, GW150914 discovery papers]



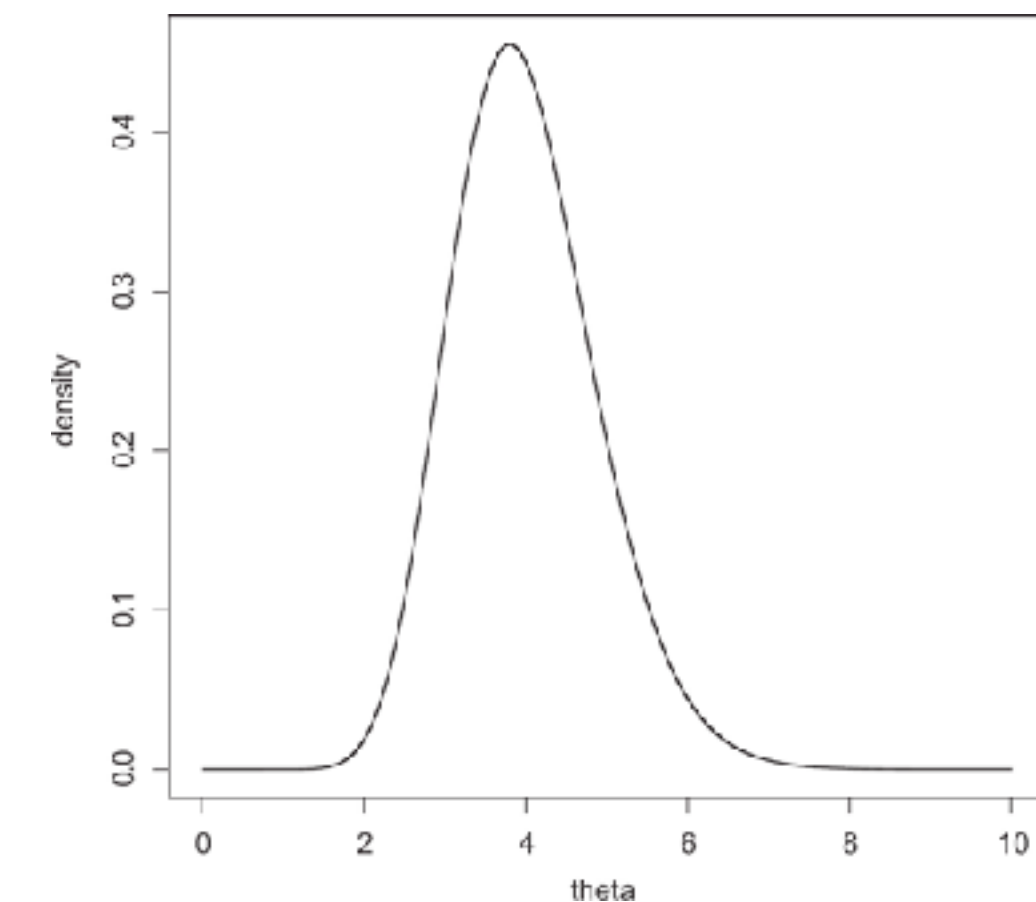
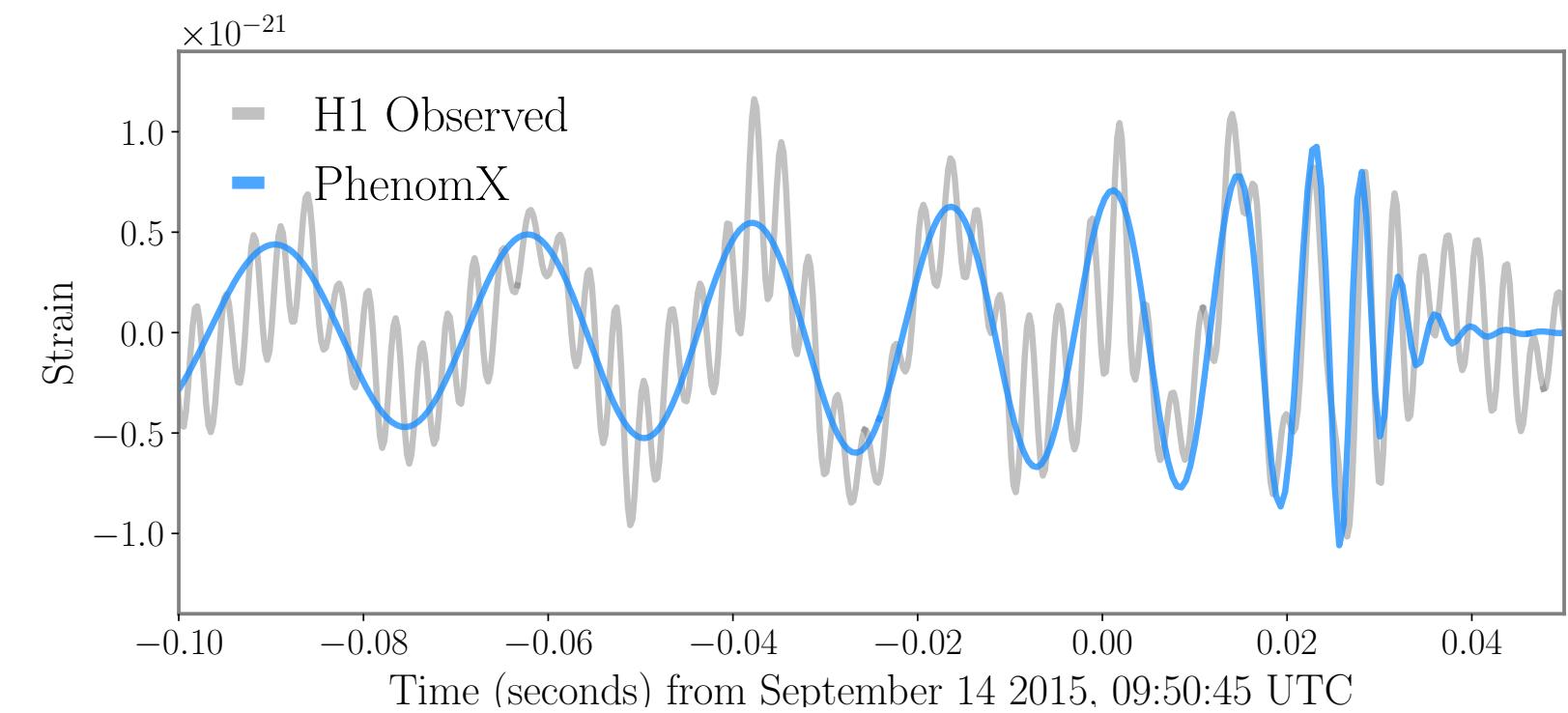
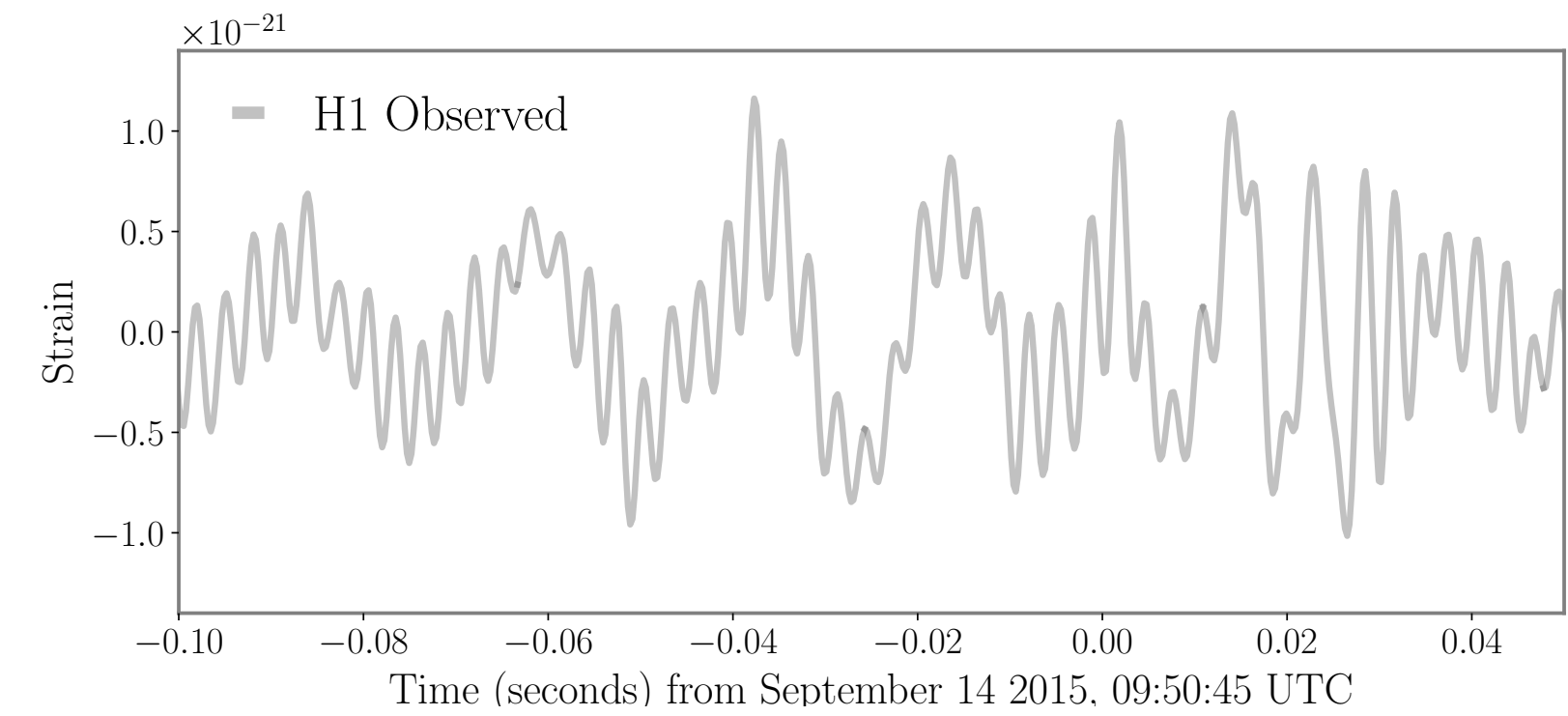
MEASURING BINARY PARAMETERS

- ▶ GW signal encodes the astrophysical information: masses, spins, tides, location, orientation of the orbit
- ▶ Use **Bayesian inference** to infer the source parameters θ :

Posterior Probability

$$p(\theta | d) = \frac{\mathcal{L}(d | \theta) \pi(\theta)}{\mathcal{Z}}$$

Likelihood Priors
Evidence

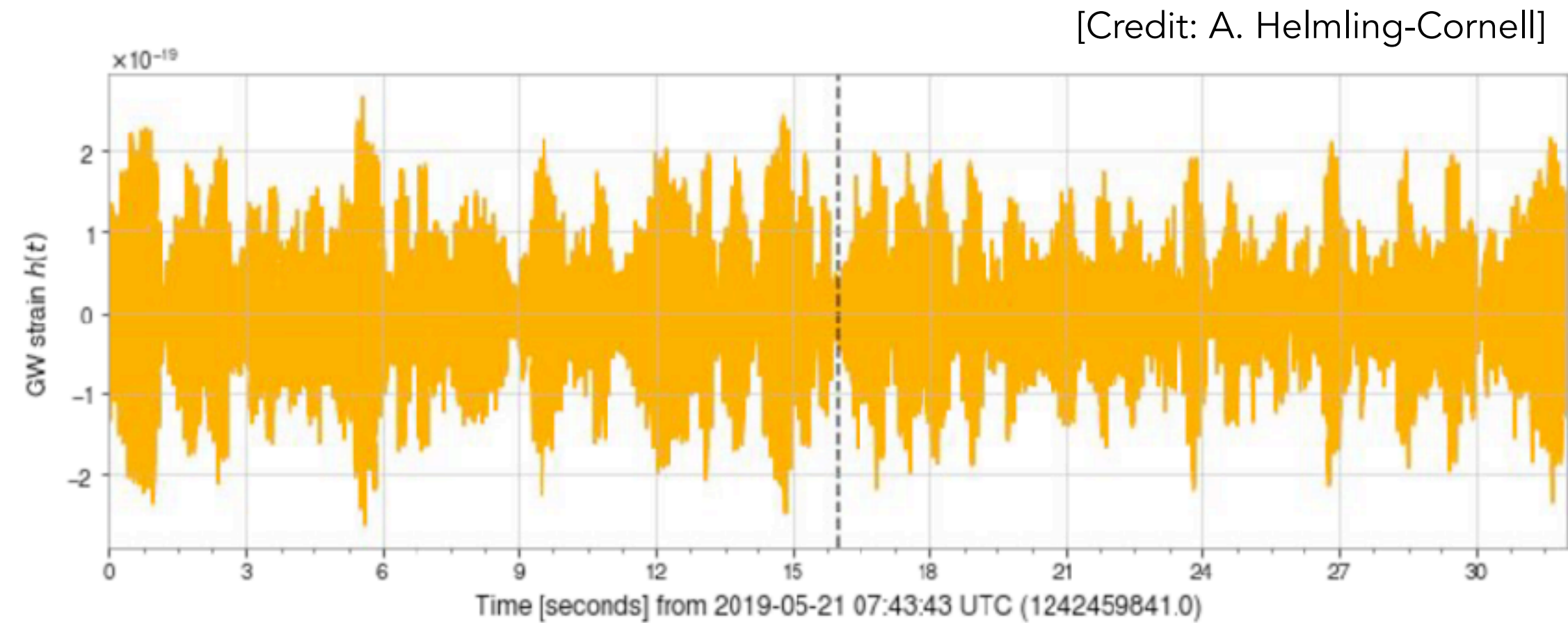


Slide credit: G. Pratten



THE DATA

- ▶ For an incident signal, a GW detector records the following data:



$$d = R(h) + n$$

data

noise

detector response to a GW

- ▶ Real-valued detector response to a GW:

$$R(h) = F_+(\alpha, \delta, \psi)h_+ + F_\times(\alpha, \delta, \psi)h_\times$$

THE NOISE

- ▶ Three key assumptions:

- ▶ **Gaussian** with zero mean and known variance

$$p(n) \propto \exp \left(-\frac{1}{2} \sum_{i,j} n_i C_{ij}^{-1} n_j \right)$$

noise correlation matrix

- ▶ **Stationary**

$$C_{ij} = \frac{1}{2} S_n(f_i) \delta_{ij}$$

power spectral density


- ▶ **Independent** between frequency bins and detectors



LIKELIHOOD

- ▶ We are free to choose the likelihood
- ▶ In GW astronomy we assume a likelihood associated with **stationary Gaussian noise** that has zero mean and a known variance:

$$\mathcal{L}(d|\theta, H, S_n(f)) = \exp \left(\sum_i -\frac{2|\tilde{h}_i(\theta) - \tilde{d}_i|^2}{TS_n(f_i)} - \frac{1}{2} \log (\pi T S_n(f_i)/2) \right)$$


waveform template

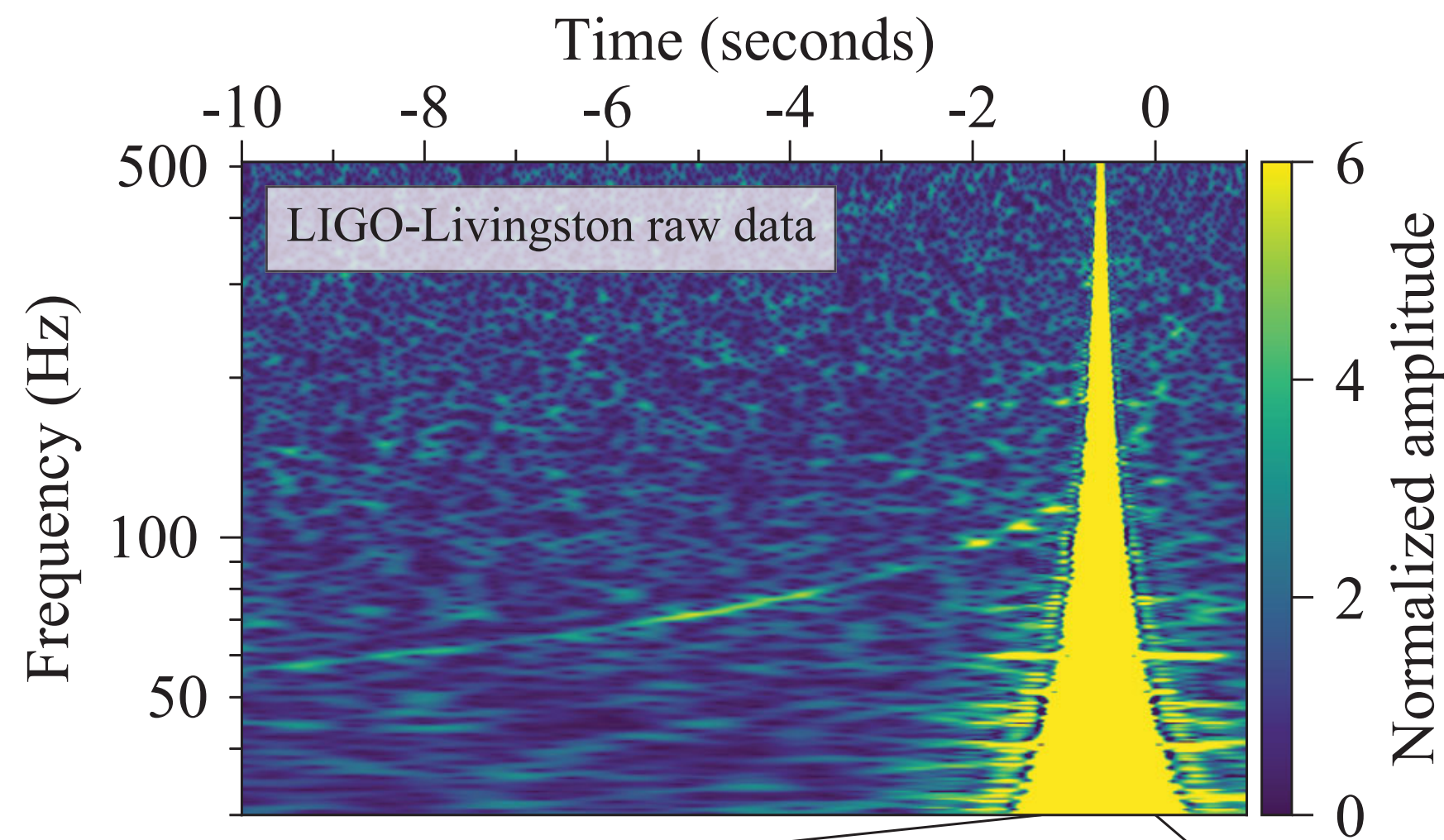
- ▶ Likelihood compares theoretical models against the data
- ▶ For a network of GW detectors:

$$\mathcal{L}(d_{\text{NW}}|\theta, H, S_{n\text{NW}}(f)) = \prod_{i \in \text{NW}} \mathcal{L}(d_i|\theta, H, S_{ni}(f))$$



STATIONARY & GAUSSIAN?

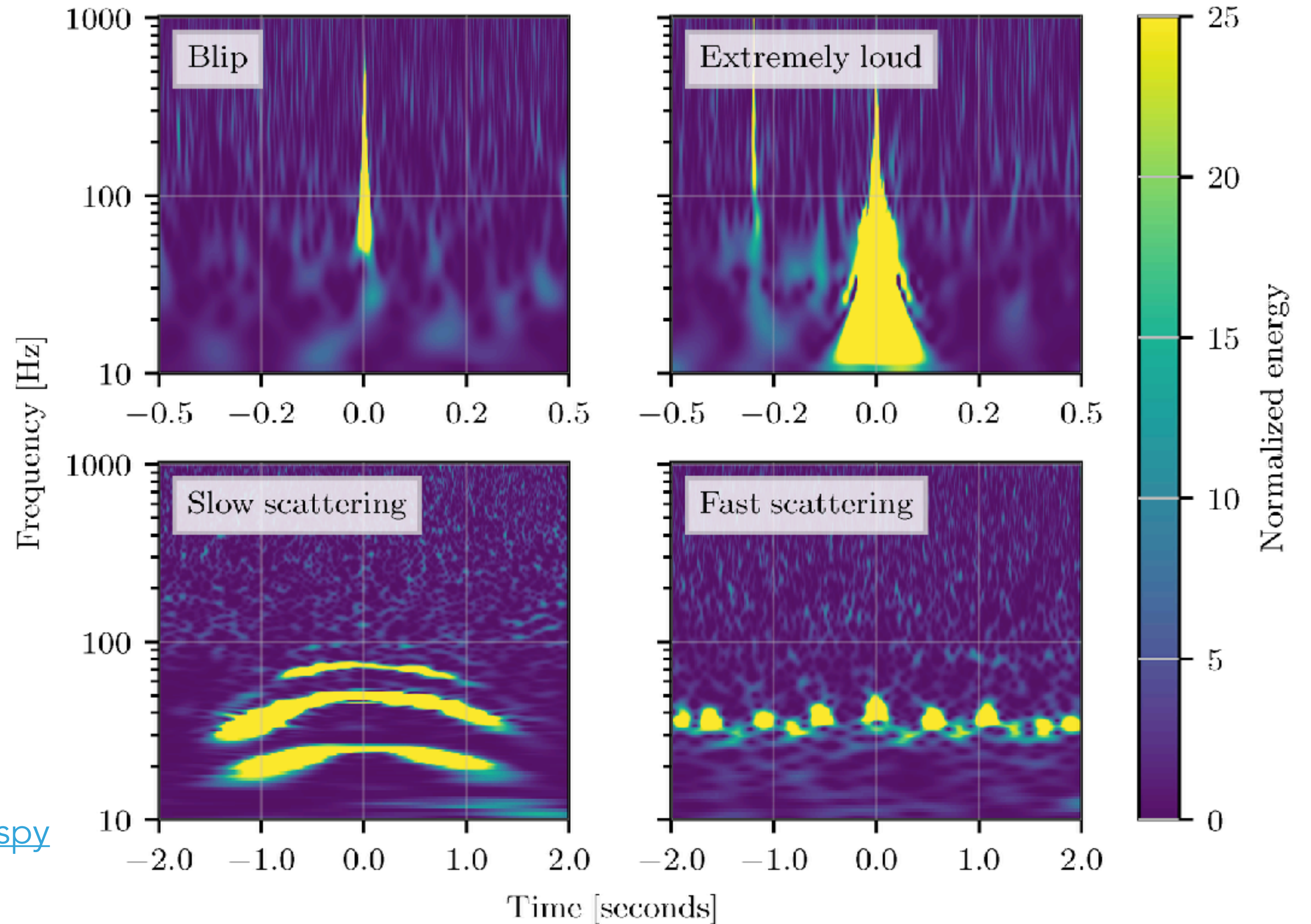
- ▶ Data cleaning
- ▶ Glitch removal/mitigation



Citizen science: Gravity Spy

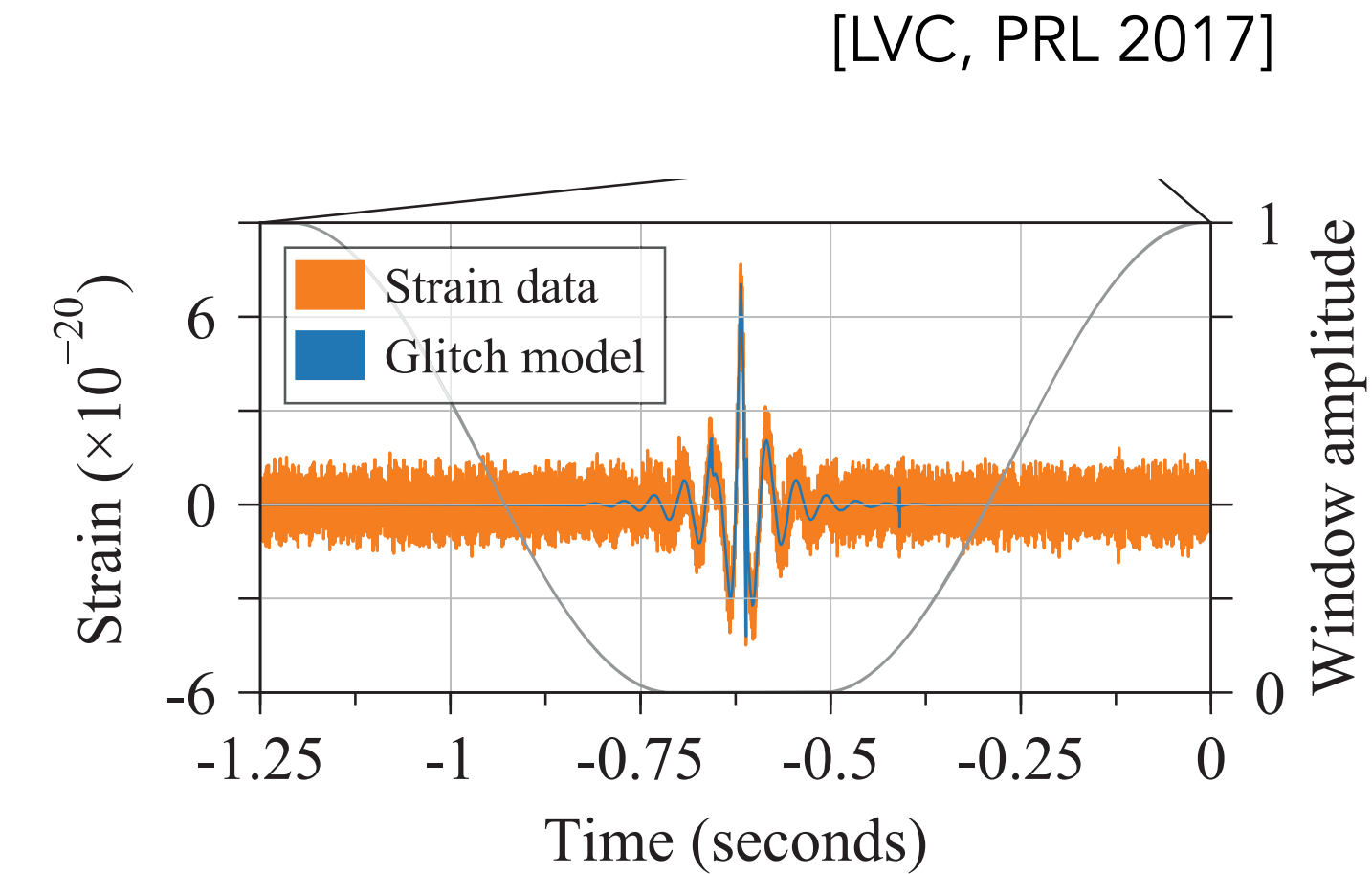
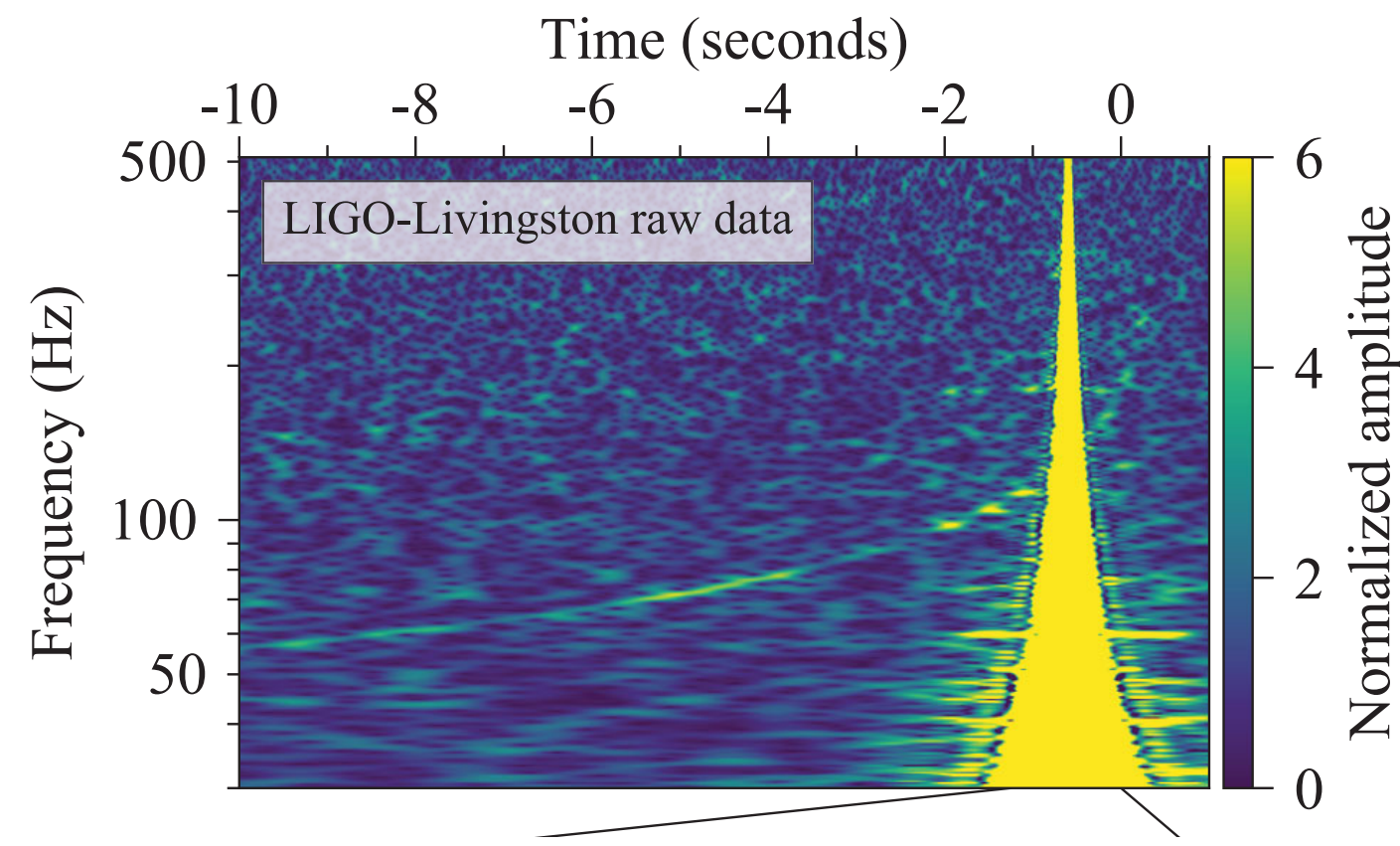
<https://www.zooniverse.org/projects/zooniverse/gravity-spy>

Some example "glitches"



GAUSSIANTY

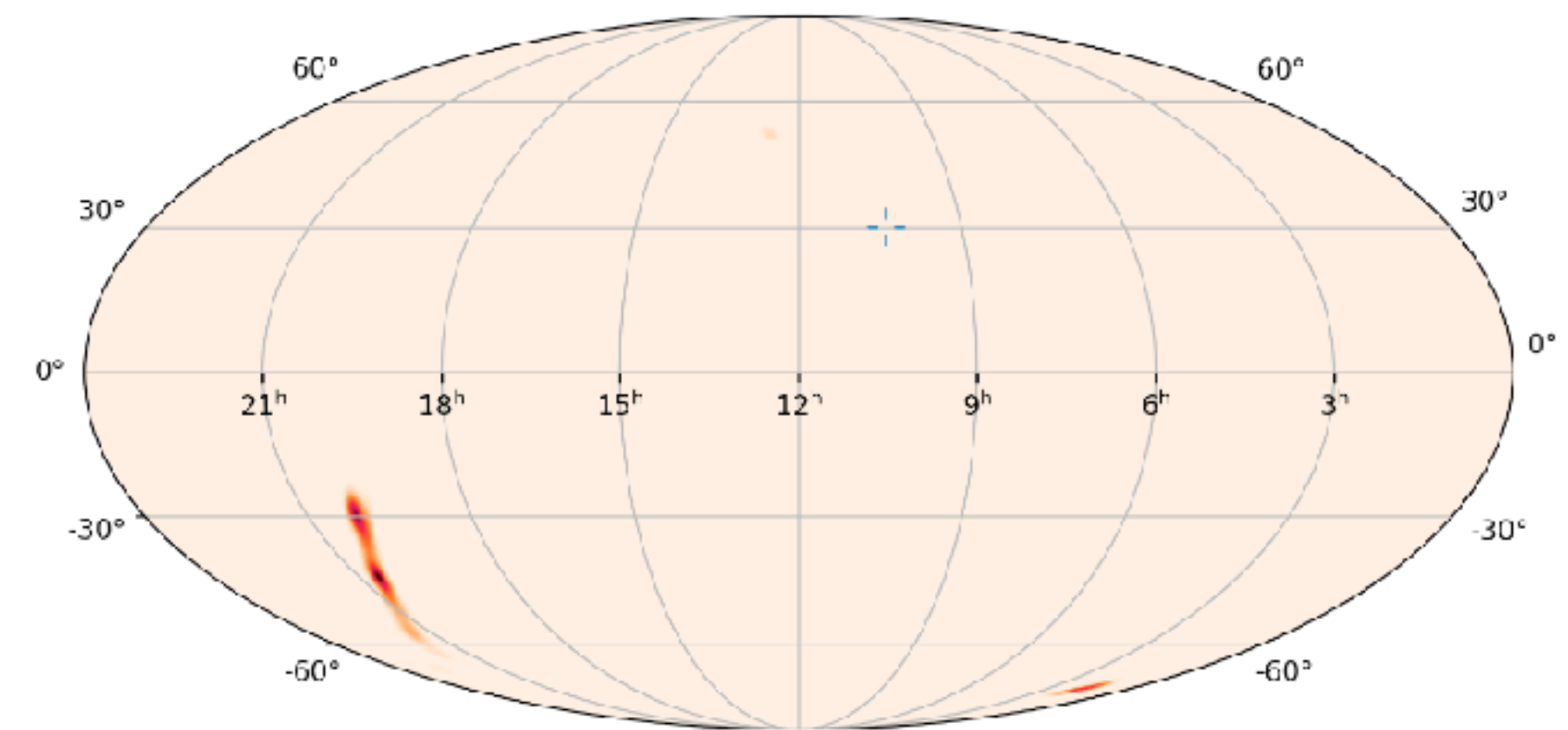
- ▶ Real detector noise often contains **non-Gaussianities** (“glitches”)
 - ▶ O3: 24% of GW candidates near glitches
 - ▶ We can modify the likelihood or remove them from the data



[LVC, PRL 2017]

Example: GW170817 overlapped with a blip glitch in LIGO-Livingston

- ▶ Prominent example: GW170817
- ▶ Noise transients impact the measurement:
 - ▶ Systematic errors in sky location
 - ▶ Systematic biases in source parameters



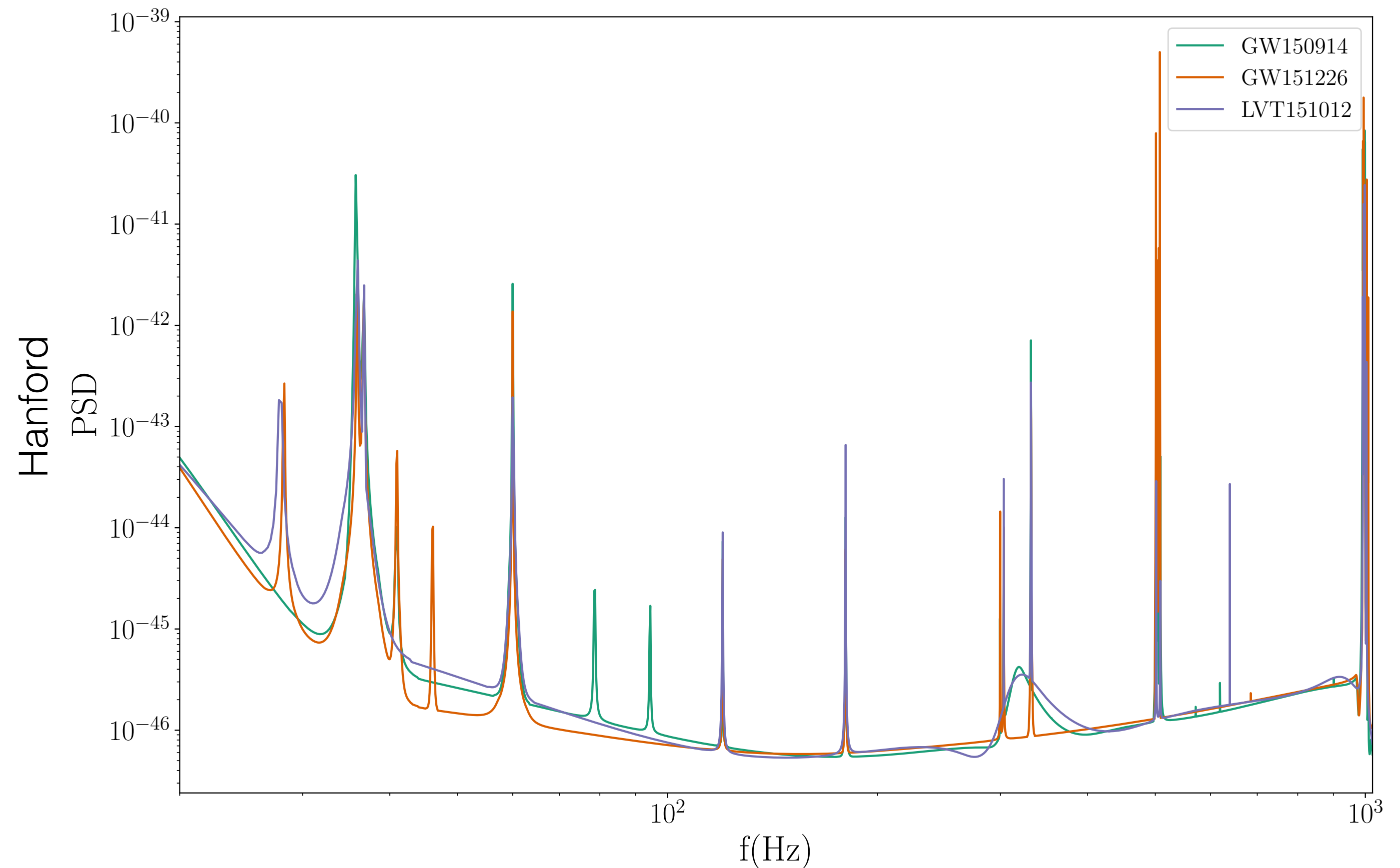
(a) Sky localisation of a GW150914-like event injected at $t_0 + 30$ ms relative to the blip glitch central time t_0 . The 90% credible area is 137 deg^2 .

[Macas+, 2022]



STATIONARITY

- ▶ The noise floor in GW detectors varies over time
 - ▶ $S_n(f)$ changes between events
 - ▶ Compute the PSD for every event to take PSD drift into account
- ▶ Note: Uncertainty in the PSD estimation can also be taken into account via marginalisation by introducing extra parameters into the noise model

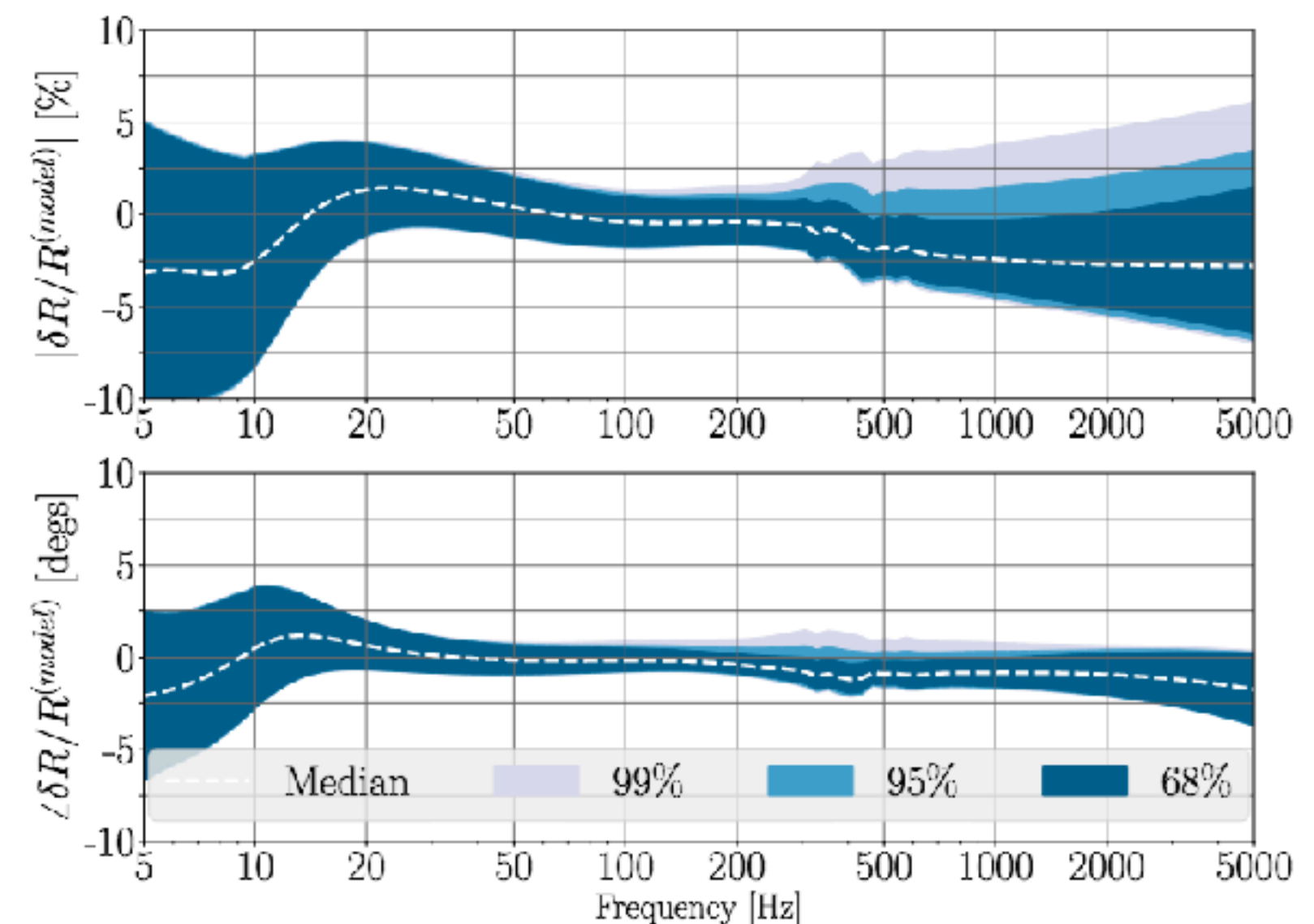
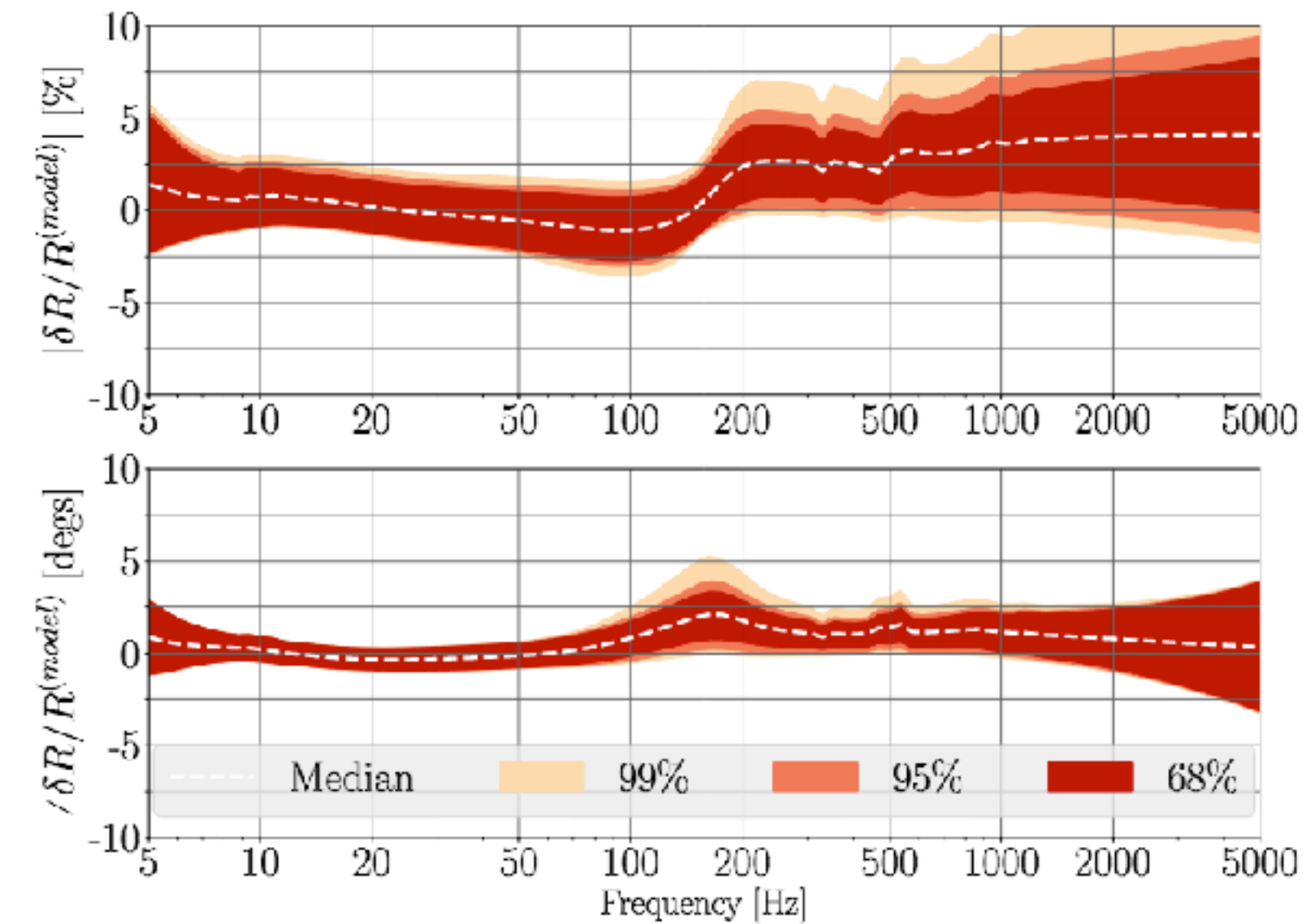


Credit: K. Chatziioannou



CALIBRATION

- ▶ Calibration quantifies the detector's response to incident GWs
 - ▶ Miscalibration results in biased strain data!
- ▶ Parameterised model for calibration uncertainty
 - ▶ Marginalised over during parameter estimation
- ▶ Calibration uncertainties are not the limiting factor in current GW observations
 - ▶ Statistical uncertainty from detector noise dominates

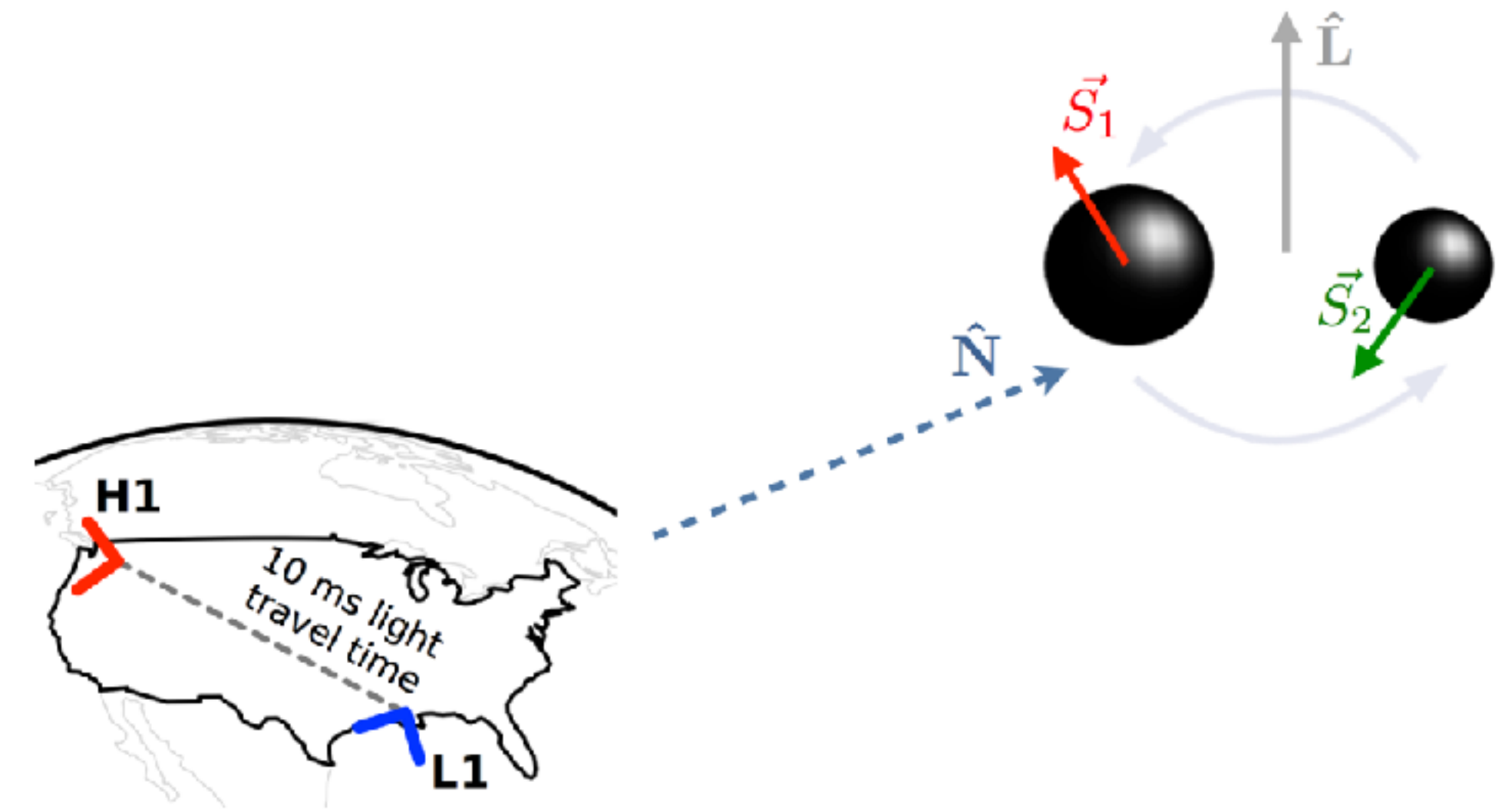


THE SIGNAL MODEL

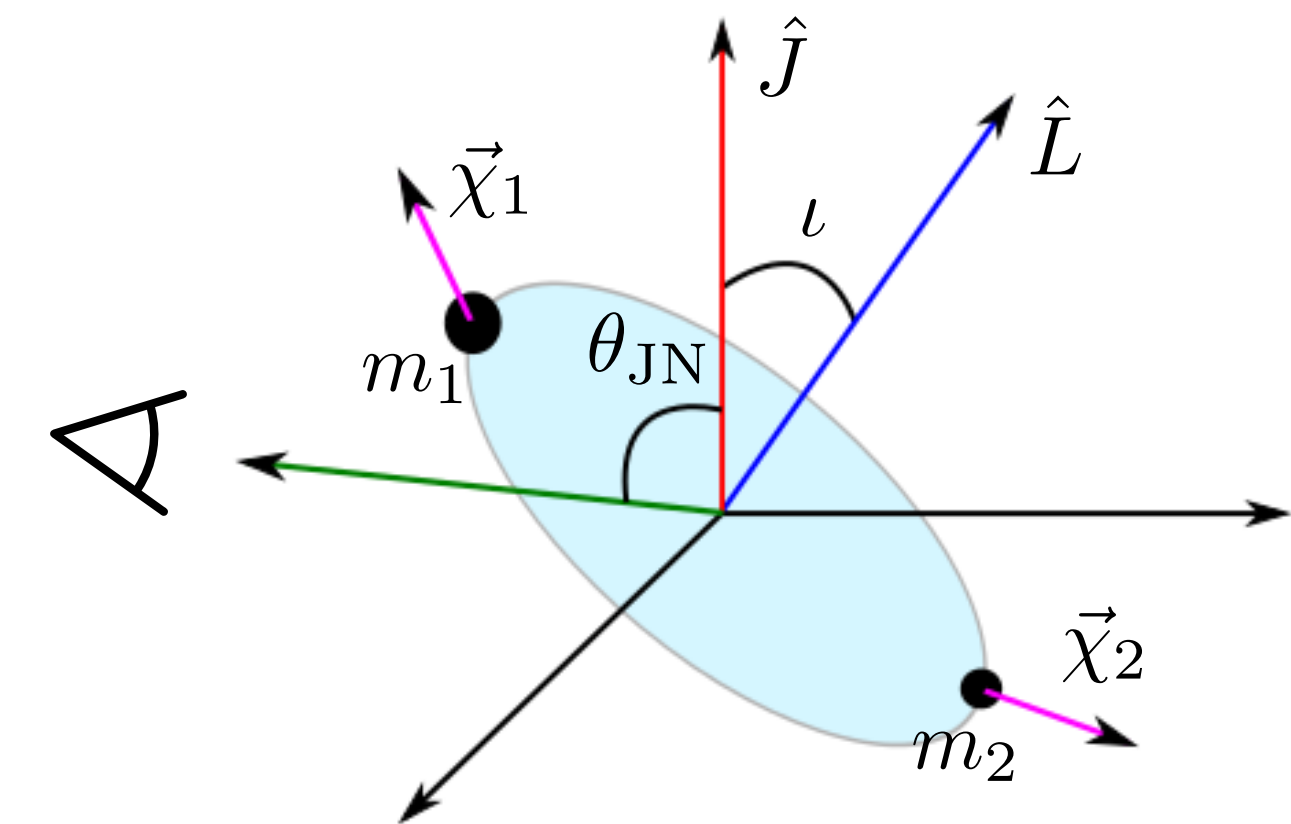
- ▶ Need a signal model $h(\theta)$ to compare against the data when evaluating the likelihood
- ▶ Circular binary black hole (15D):

$$\theta_{\text{BBH}} = \underbrace{\{m_1, m_2, \vec{\chi}_1, \vec{\chi}_2\}}_{\text{intrinsic}} \underbrace{\{D_L, \iota, \alpha, \delta, \psi, \phi_c, t_c\}}_{\text{extrinsic}}$$

- ▶ Eccentric orbits: requires two additional parameters to describe the ellipse and its orientation
- ▶ Binary neutron star: θ_{BBH} + parameters that characterise the tidal response of the star

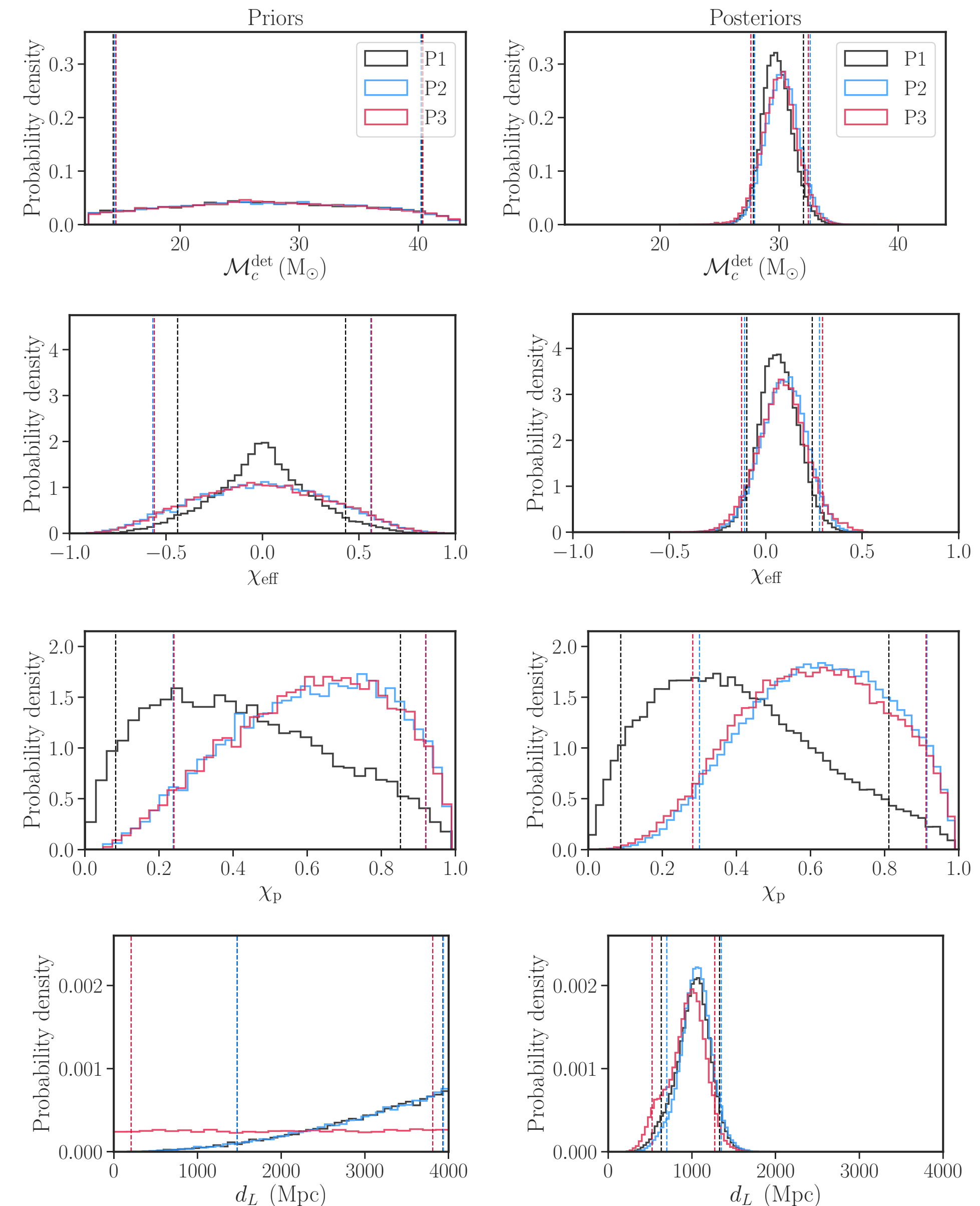


Credit: LIGO/Virgo



THE PRIOR

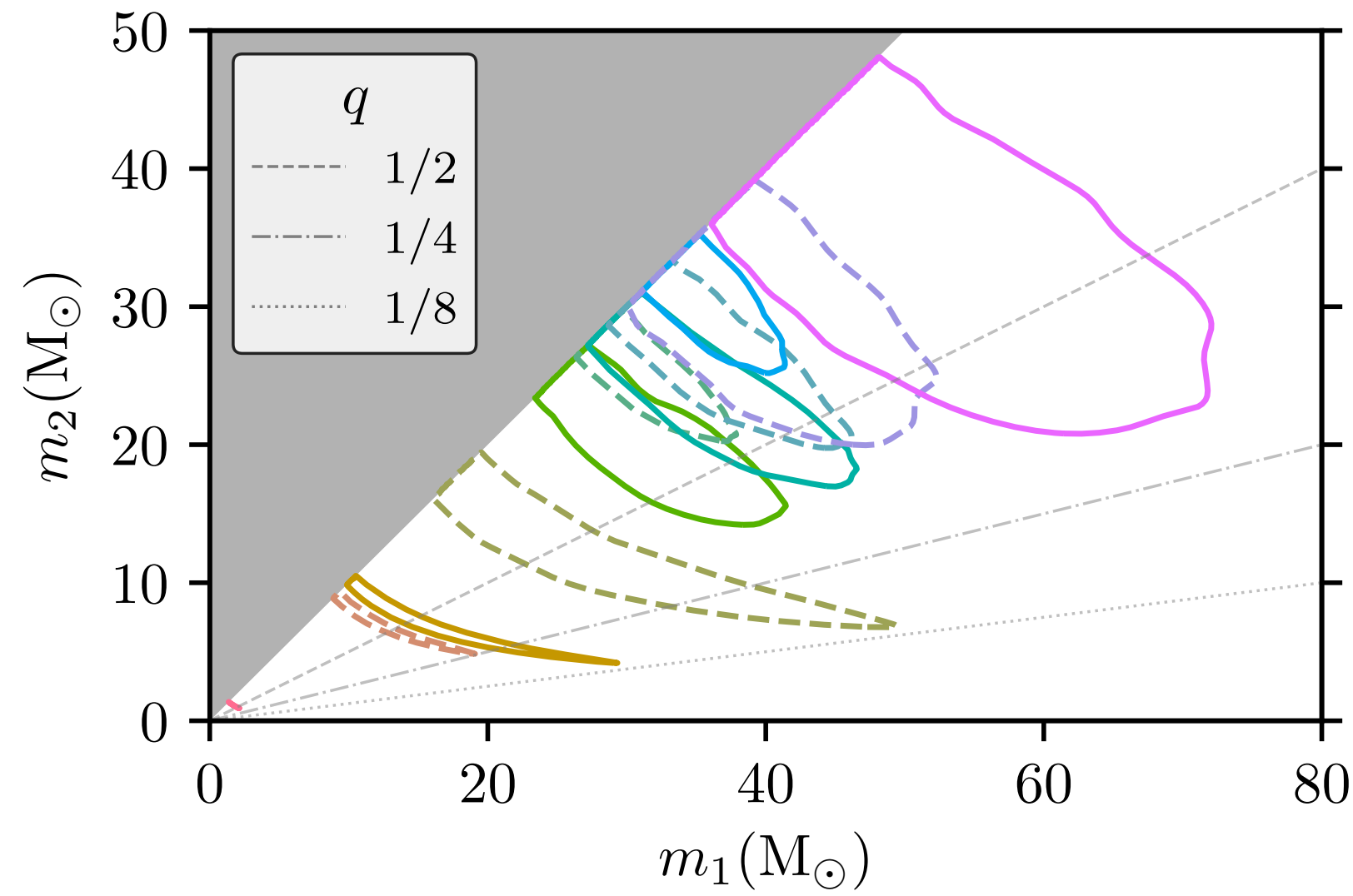
- ▶ Uninformative vs. astrophysically motivated priors
 - ▶ Population priors
- ▶ “Standard” GW priors:
 - ▶ Mass priors: often sample uniform in chirp mass $\mathcal{M}_c = \eta^{3/5} M$ & symmetric mass ratio $\eta = (m_1 m_2) / M$
 - ▶ Distance: $p(D_L) \propto D_L^2$ (uniform in “luminosity” volume)
 - ▶ Spins magnitudes: uniform
 - ▶ Spin orientation: isotropic (i.e. uniform in $\cos(\text{tilt})$)



MEASUREMENT EXAMPLES

$cS_1/(Gm_1^2)$

$cS_2/(Gm_2^2)$

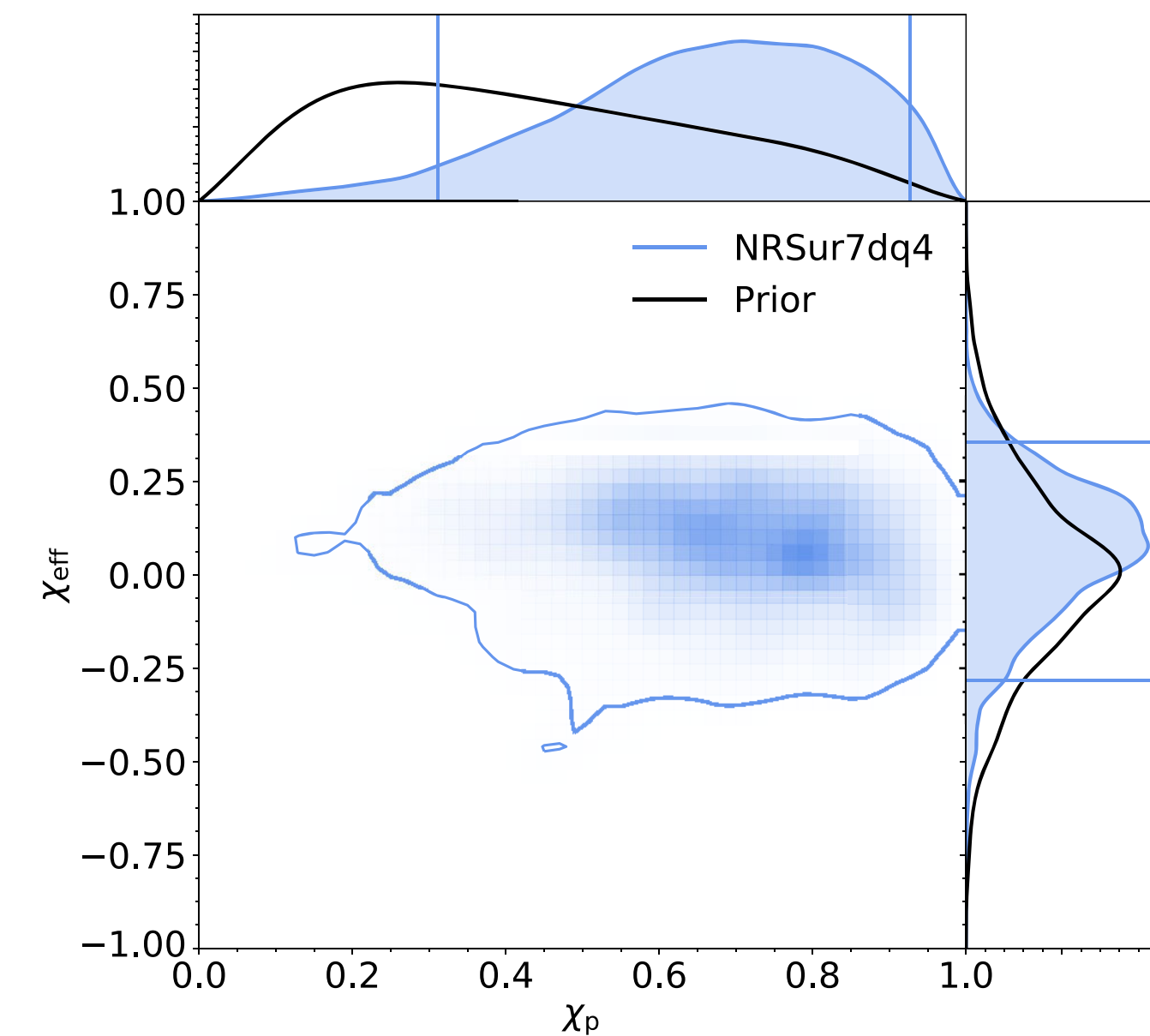
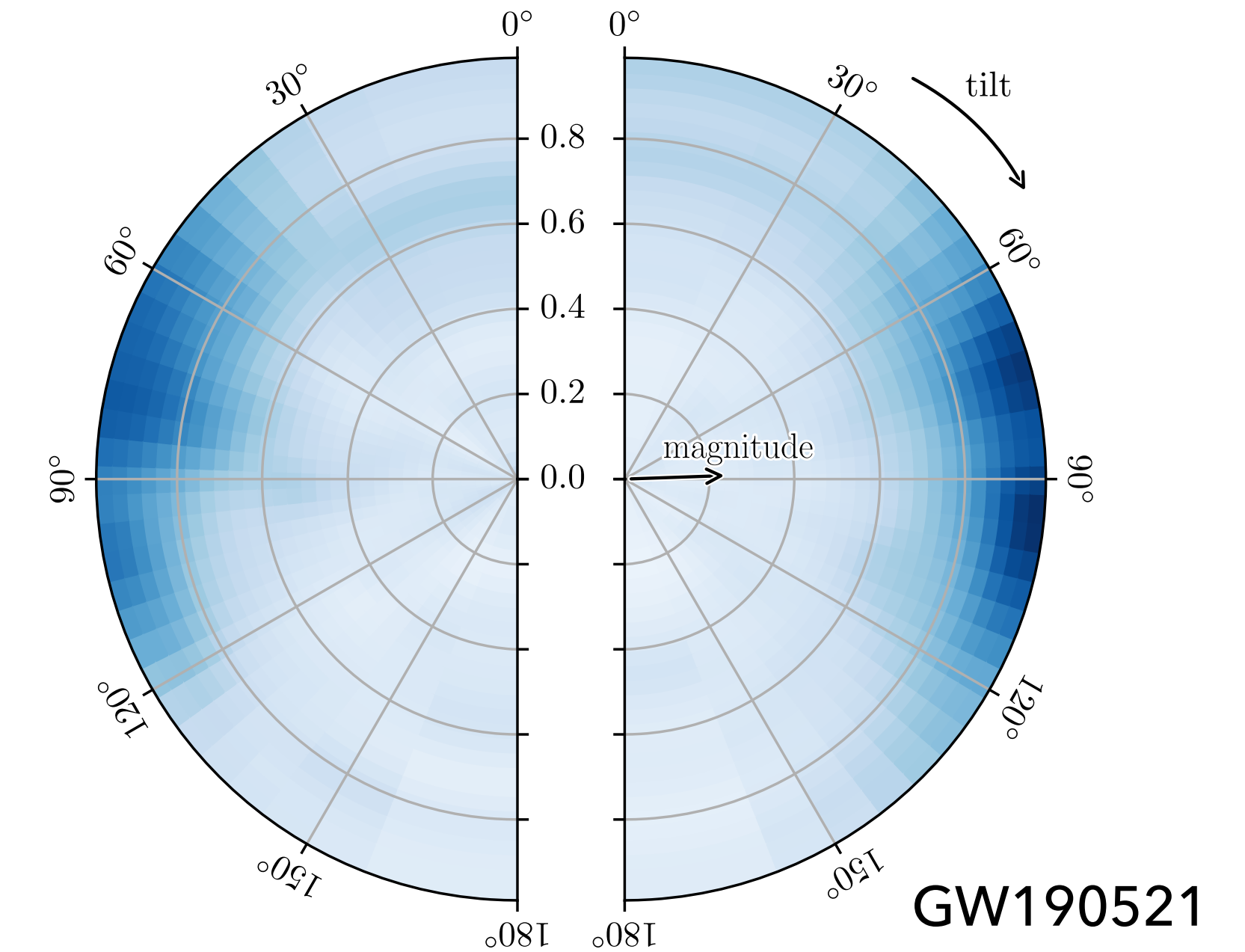
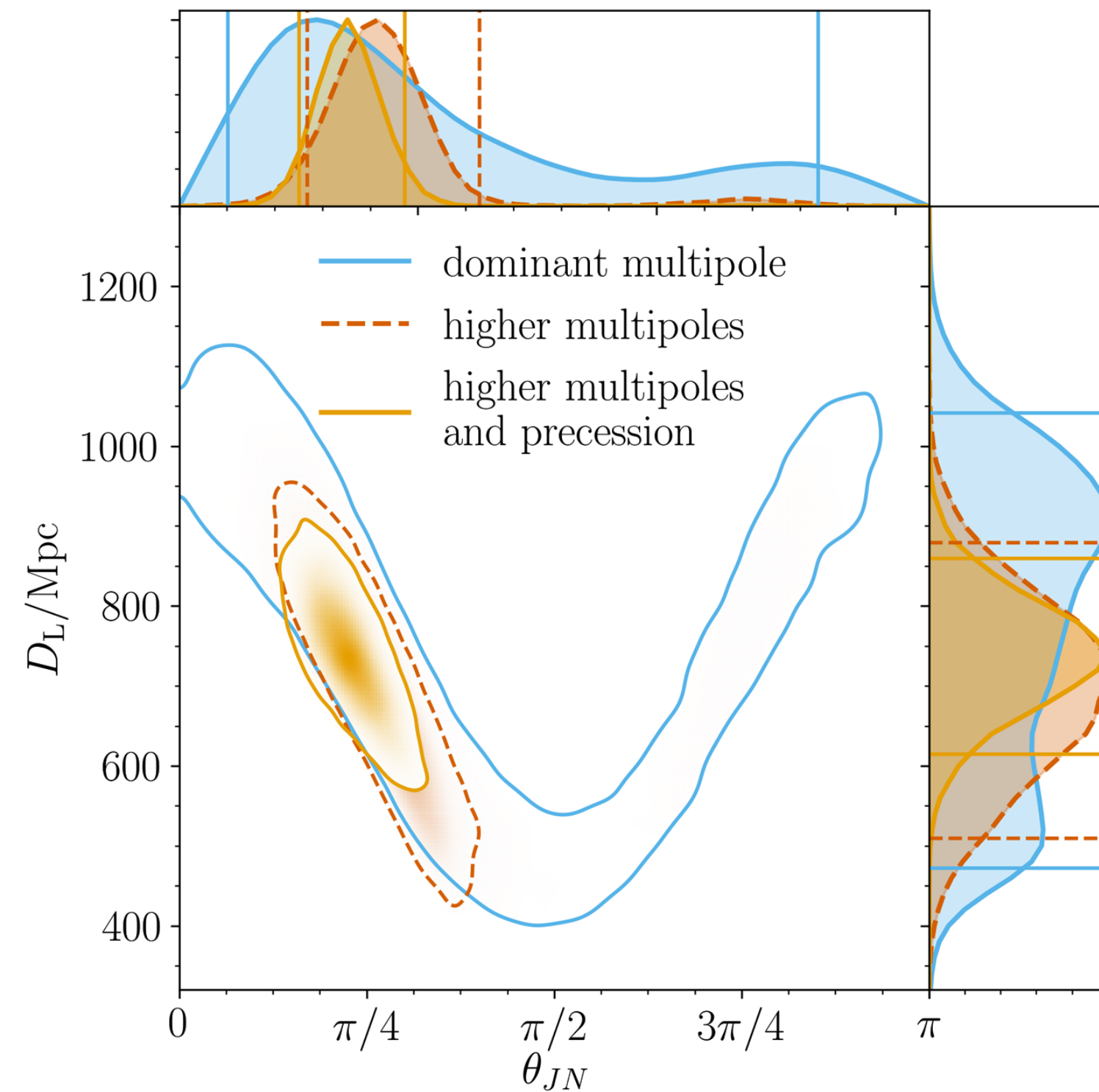


Chirp mass vs total mass

Distance-inclination degeneracy

Individual spins vs effective spins

Impact of SNR (statistical uncertainty)



[LVK: GWTC-1, GW190412, GW190521]



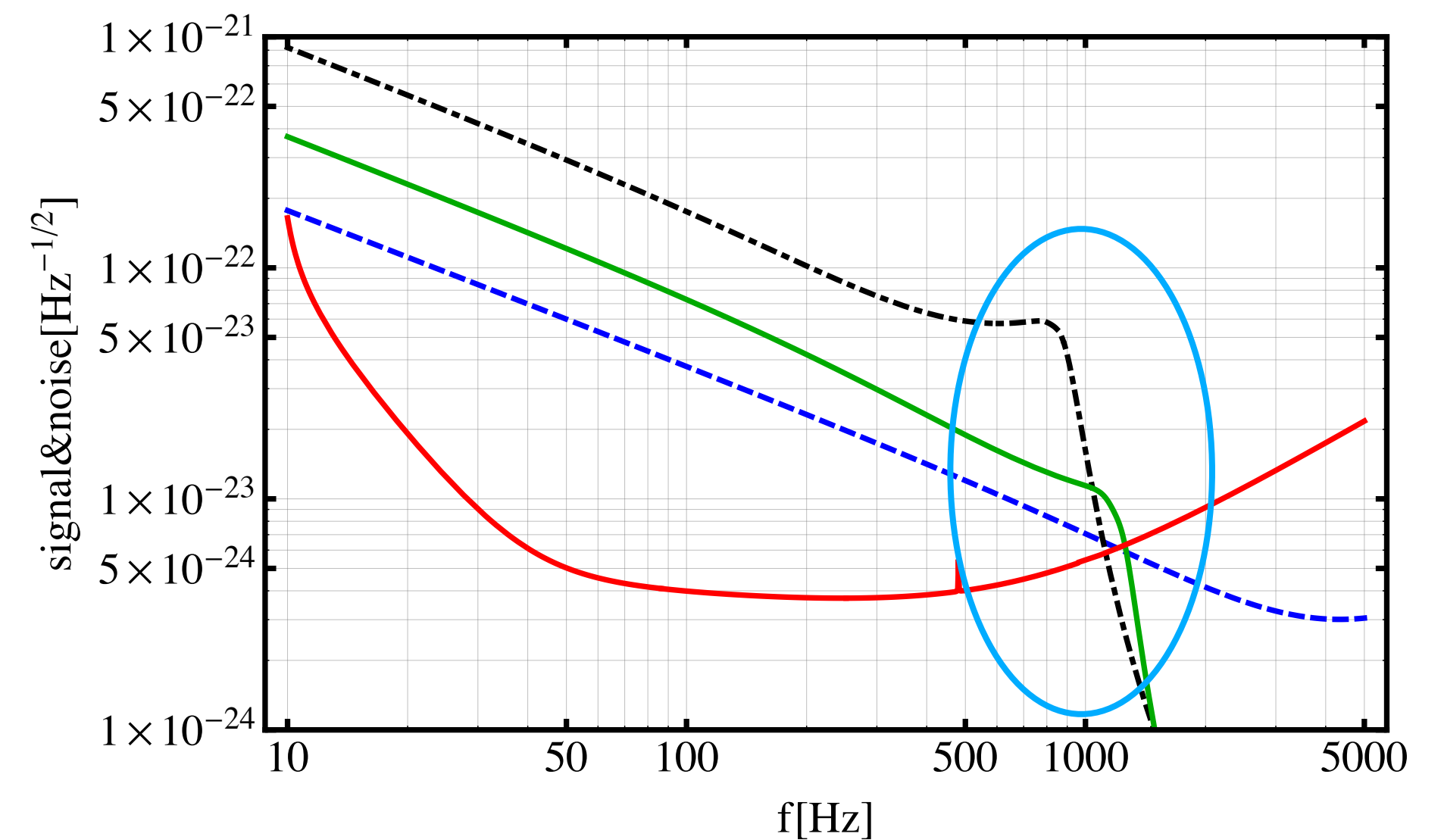
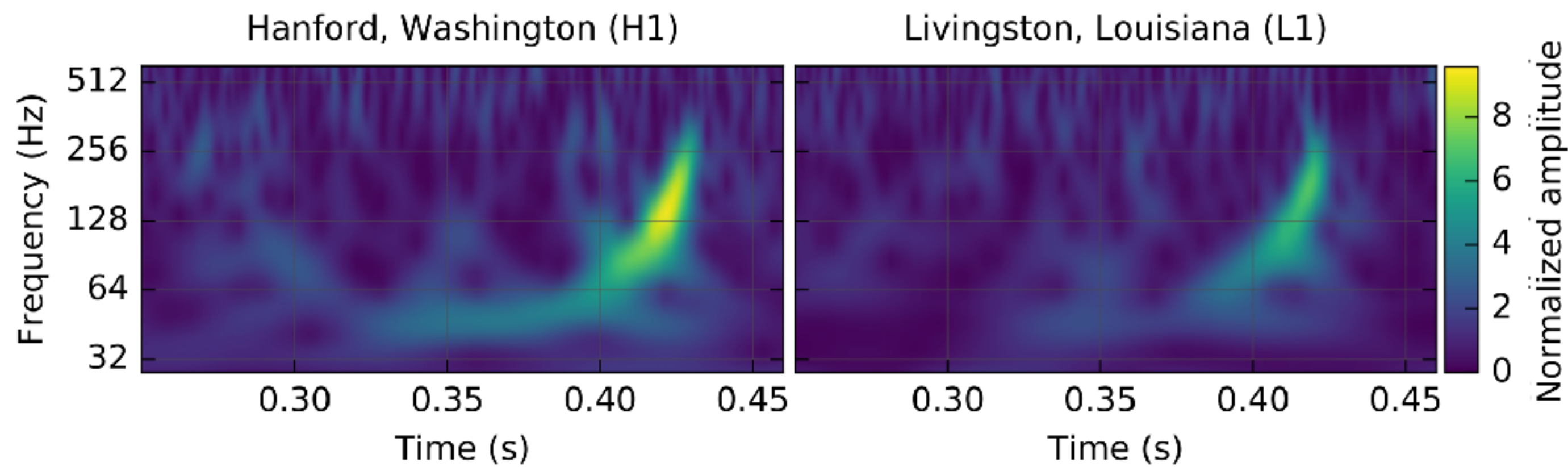
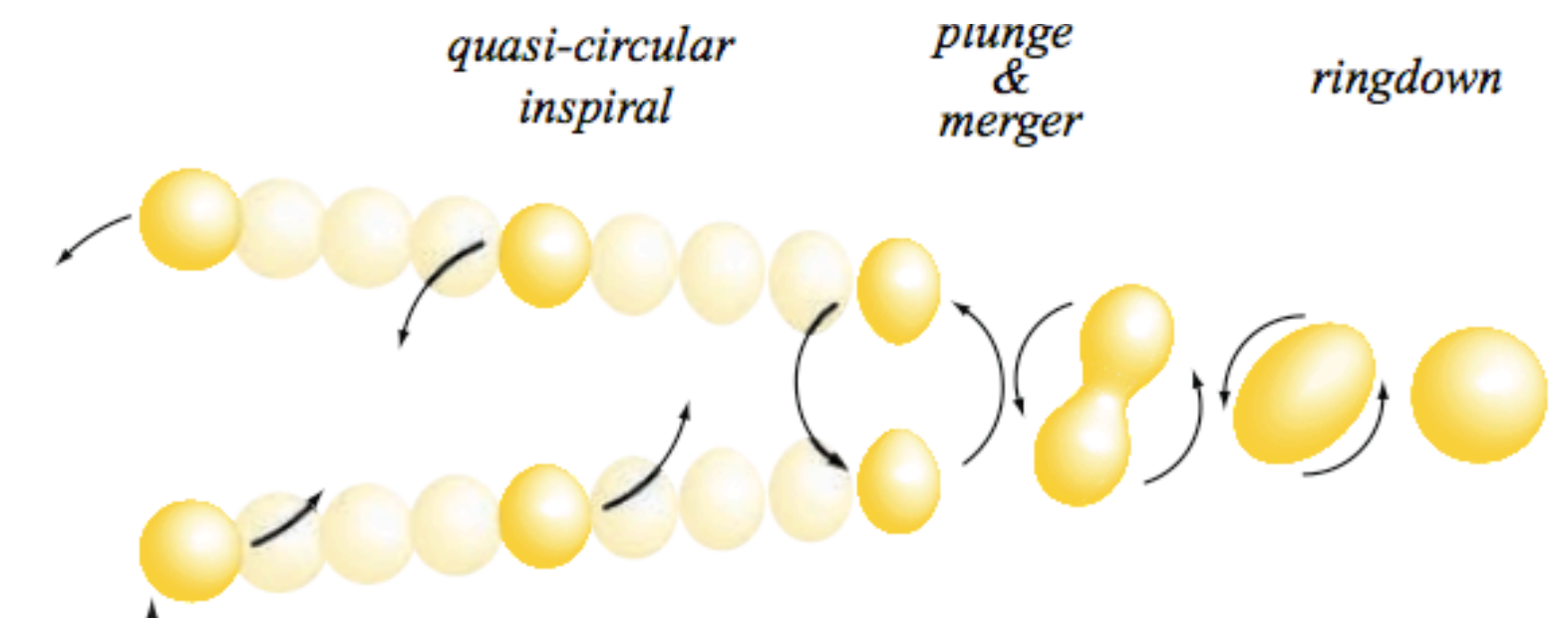
TRY IT YOURSELF :-)

- ▶ All LVK analysis software is publicly available:
<https://git.ligo.org/lscsoft/lalsuite>
- ▶ Tutorials available from the Gravitational Wave Open Science Centre: <https://gwosc.org/tutorials/>
- ▶ Perform a matched filter search: <https://pycbc.org/>
- ▶ User-friendly Python inference package Bilby:
 - ▶ Source code: <https://git.ligo.org/lscsoft/bilby>
 - ▶ Documentation: <https://lscsoft.docs.ligo.org/bilby/>

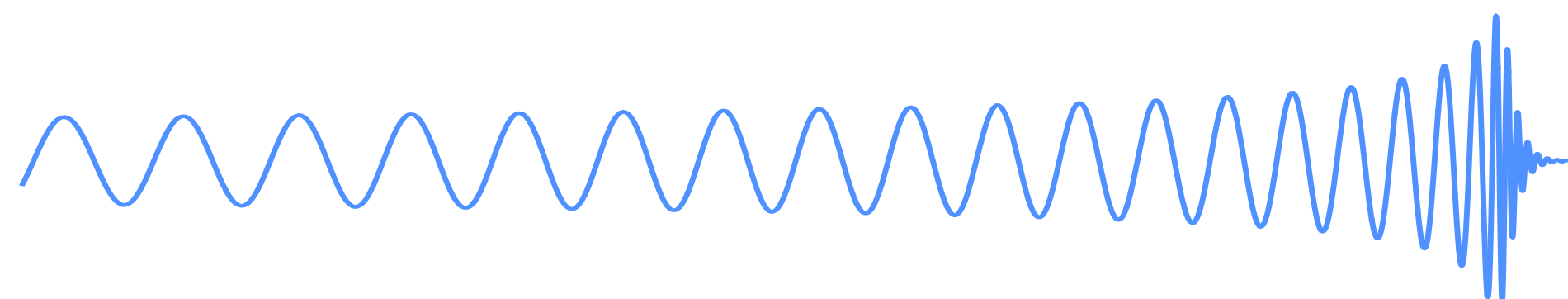


GRAVITATIONAL WAVES FROM COMPACT BINARIES

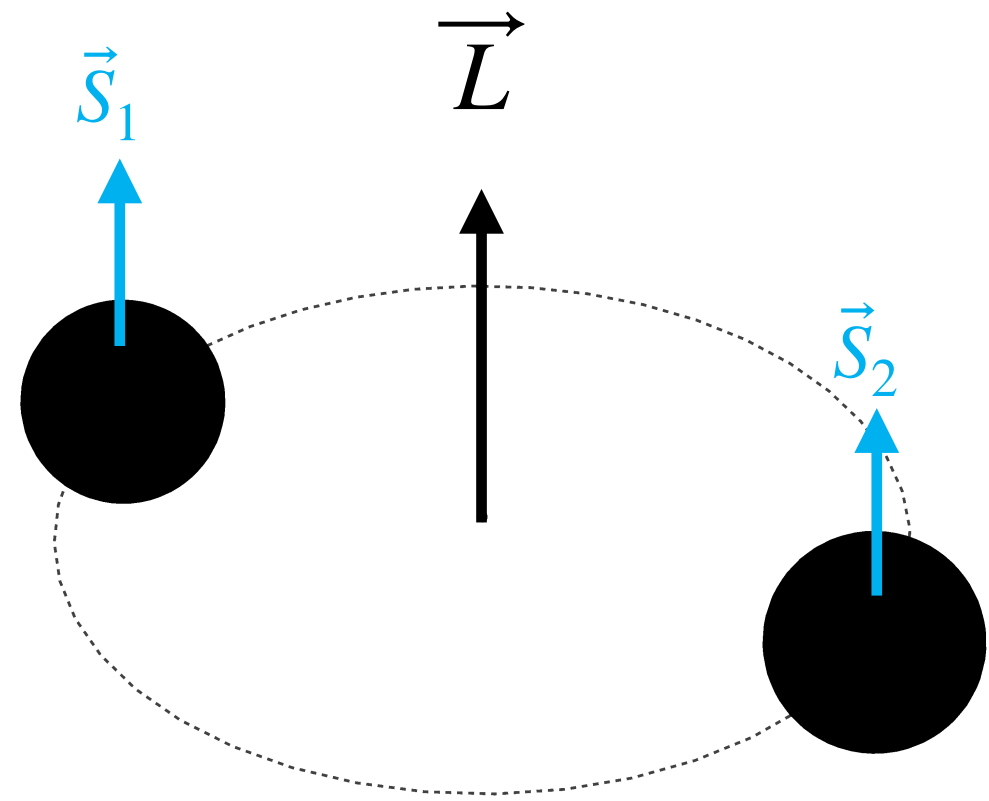
- ▶ Signal „sweeps“ through the detector’s sensitivity band
- ▶ Depending on the **total mass** of the binary, the merger regime is visible
 - ▶ Inspiral-merger-ringdown (IMR) waveforms are key
 - ▶ **Need accurate theoretical model to infer the science**



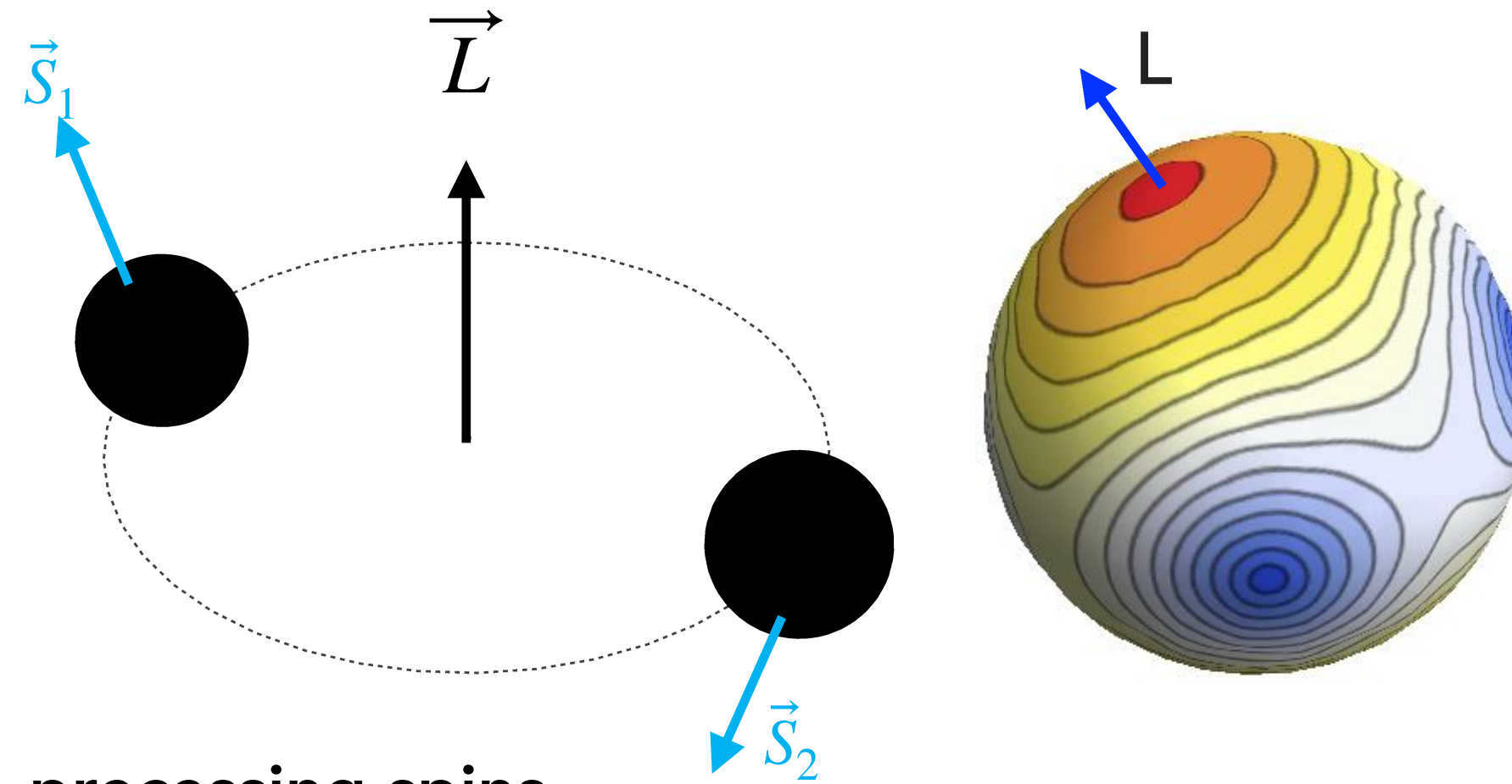
“chirp” - encodes the fundamental source properties



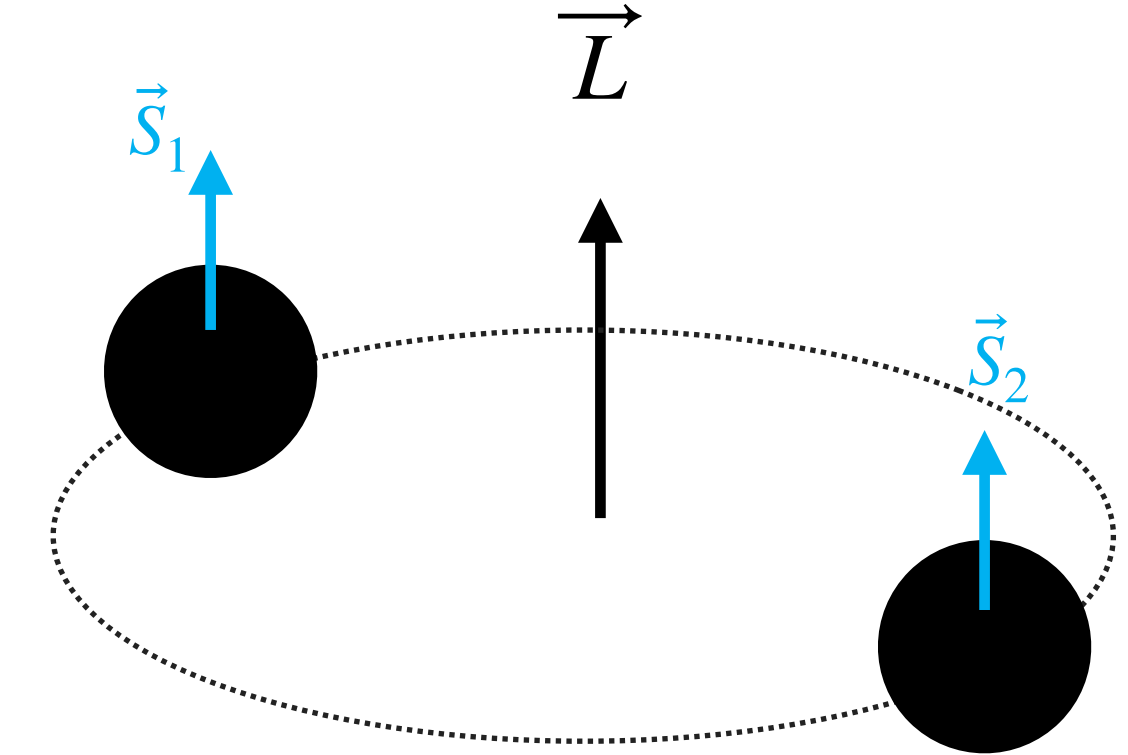
PHENOMENOLOGY



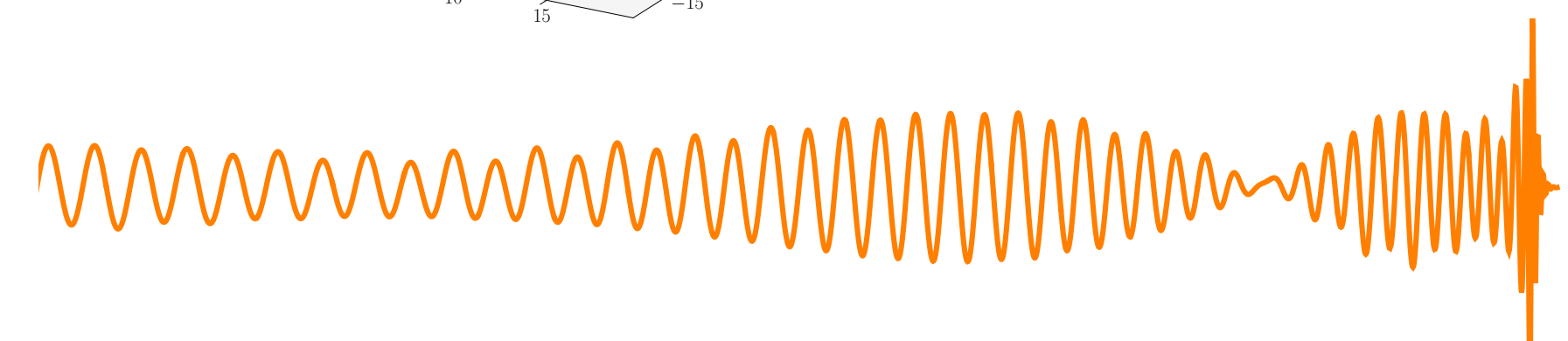
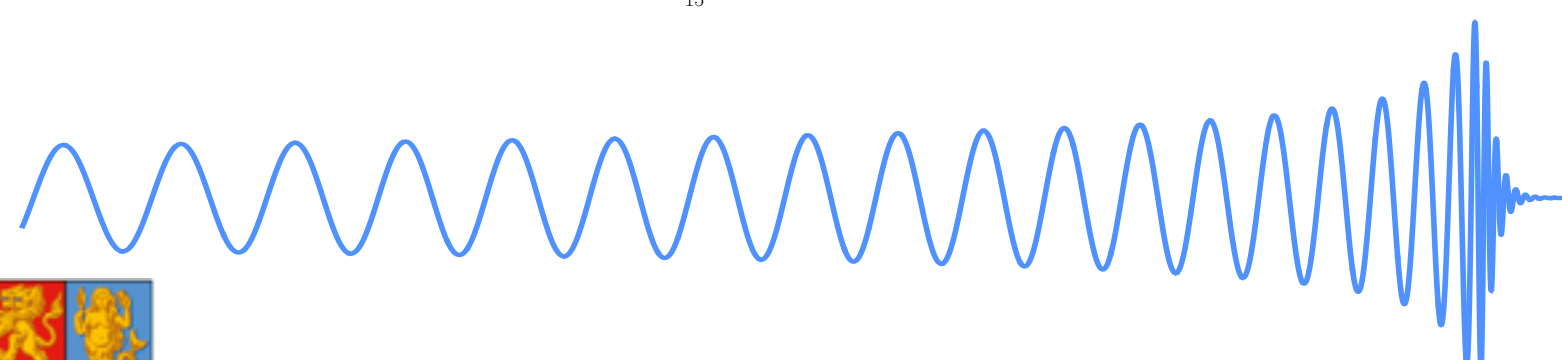
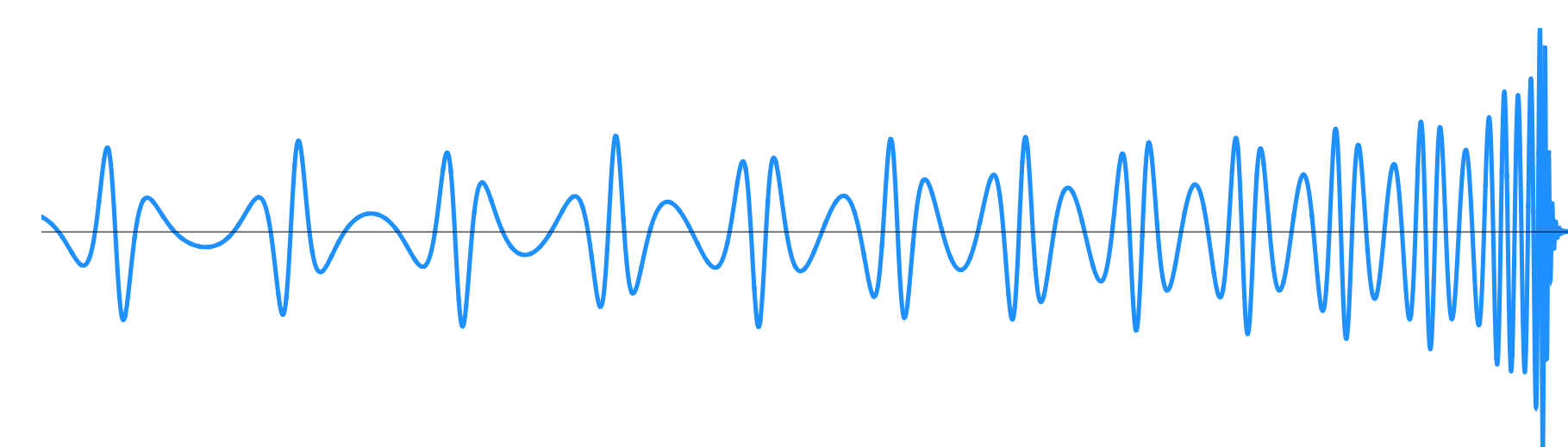
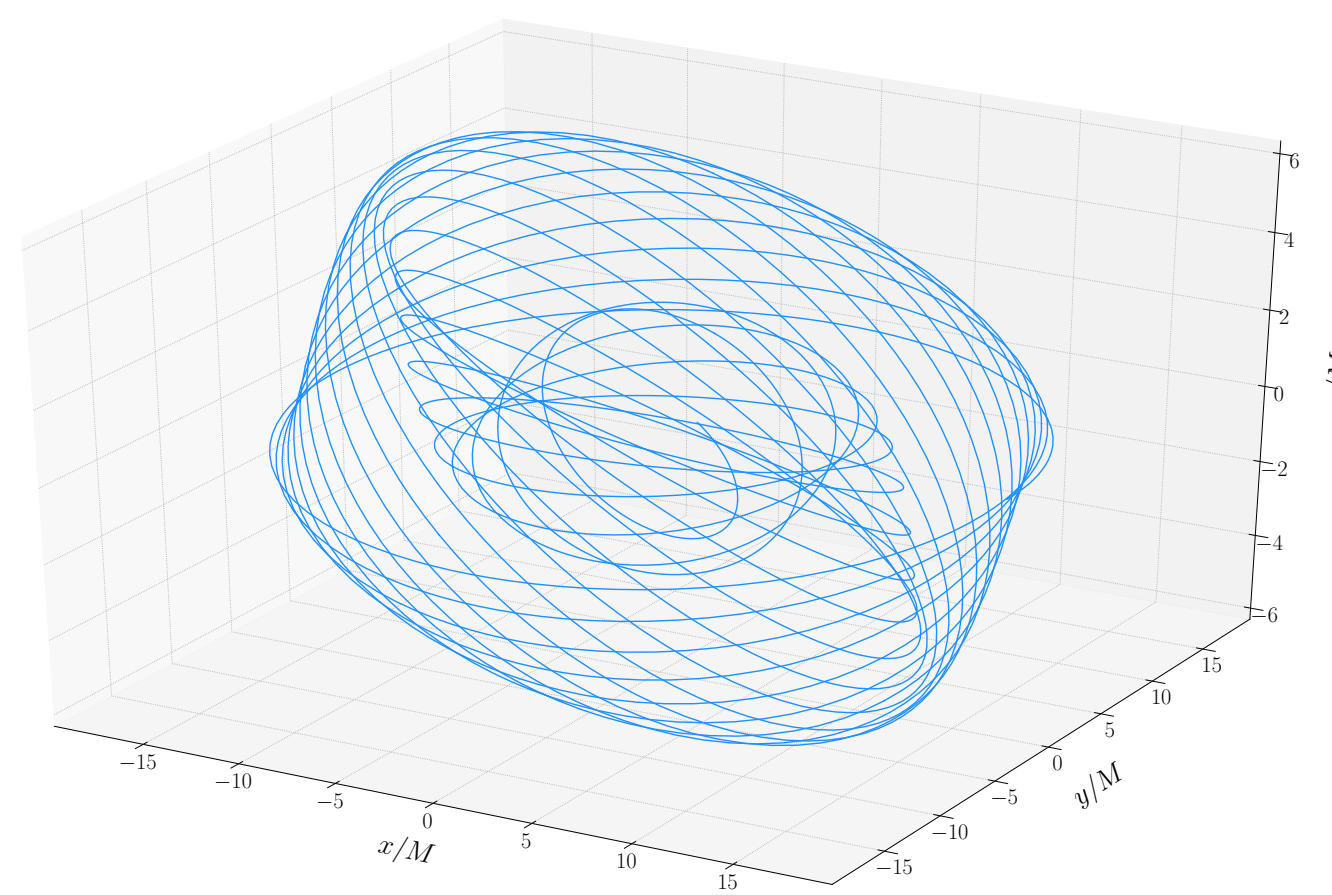
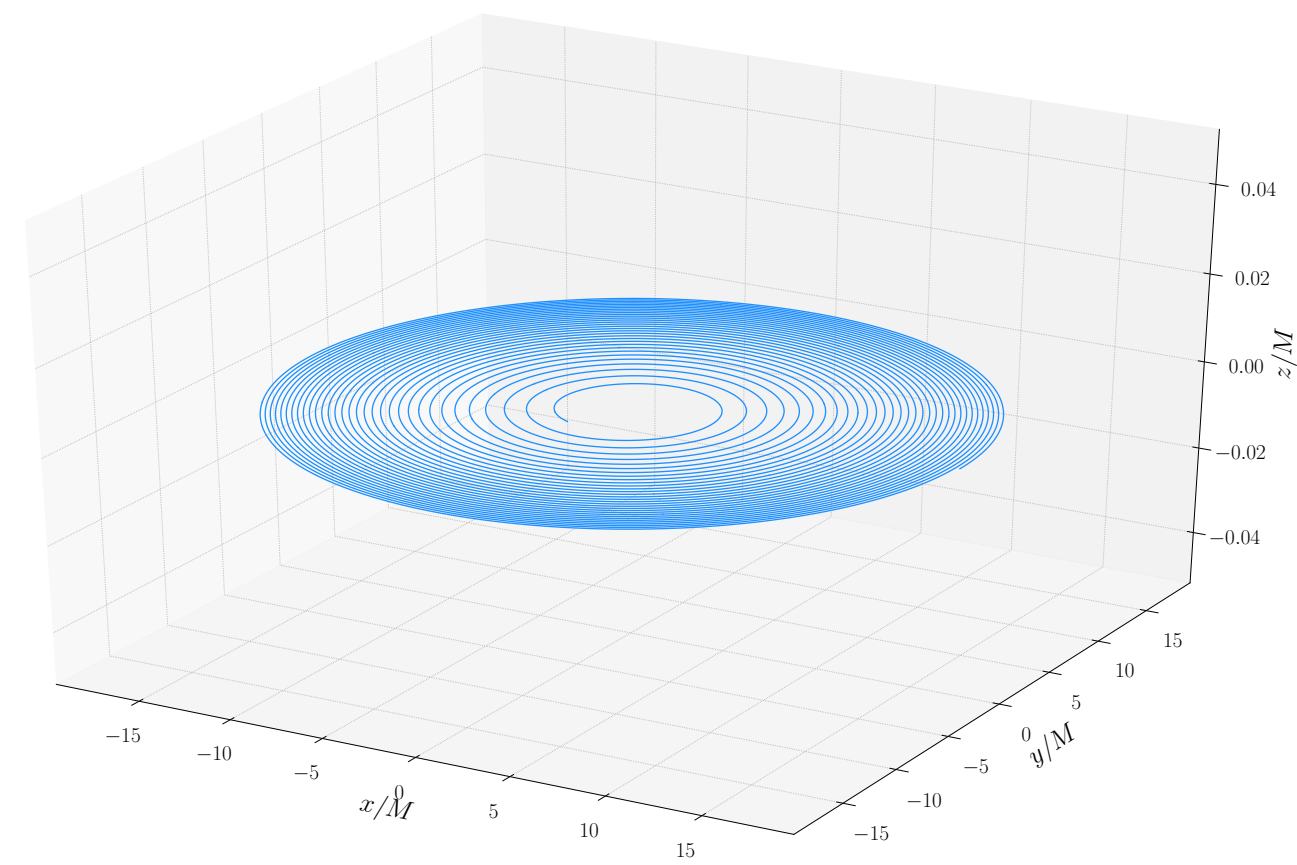
no spins or aligned spins



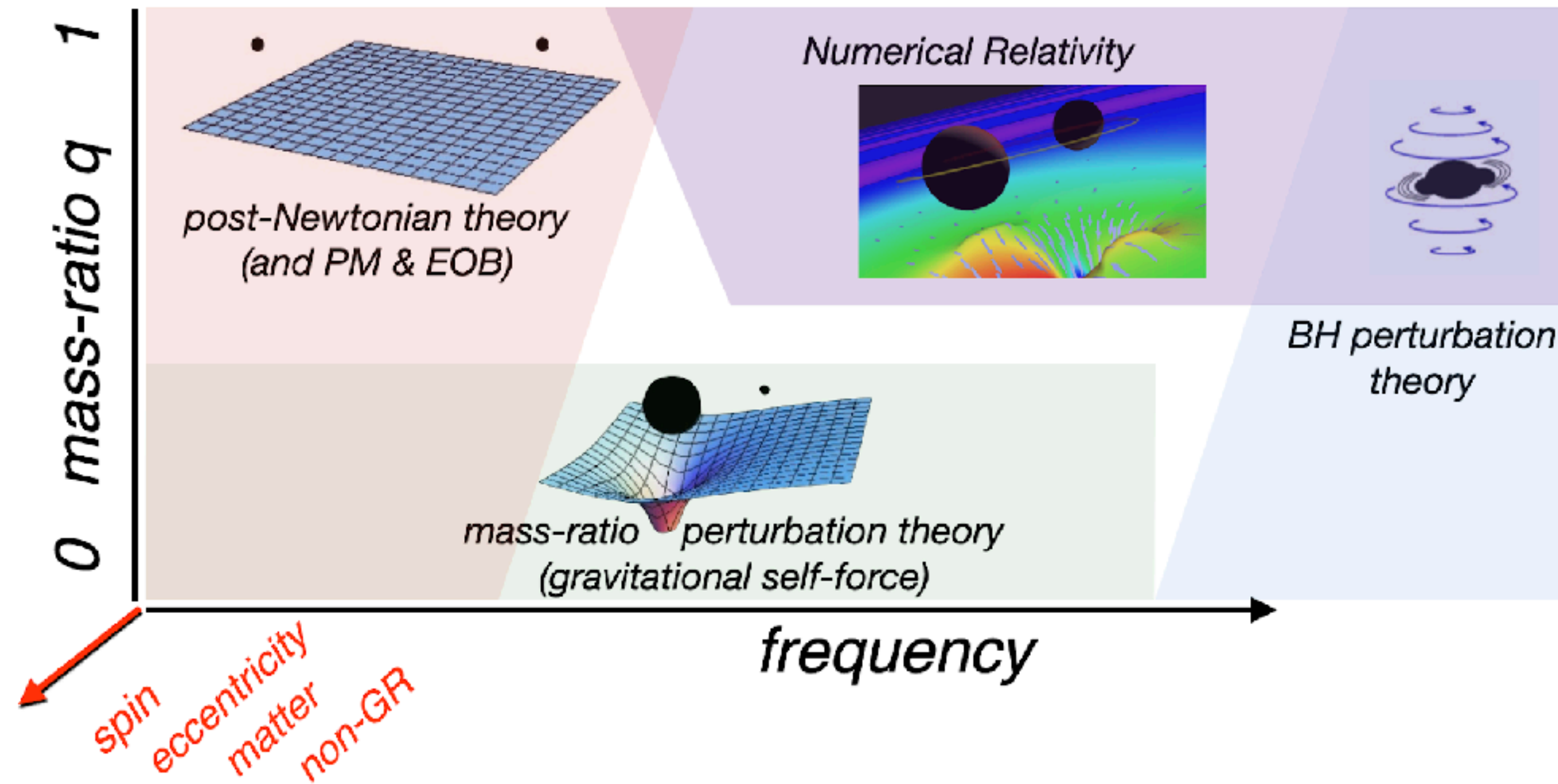
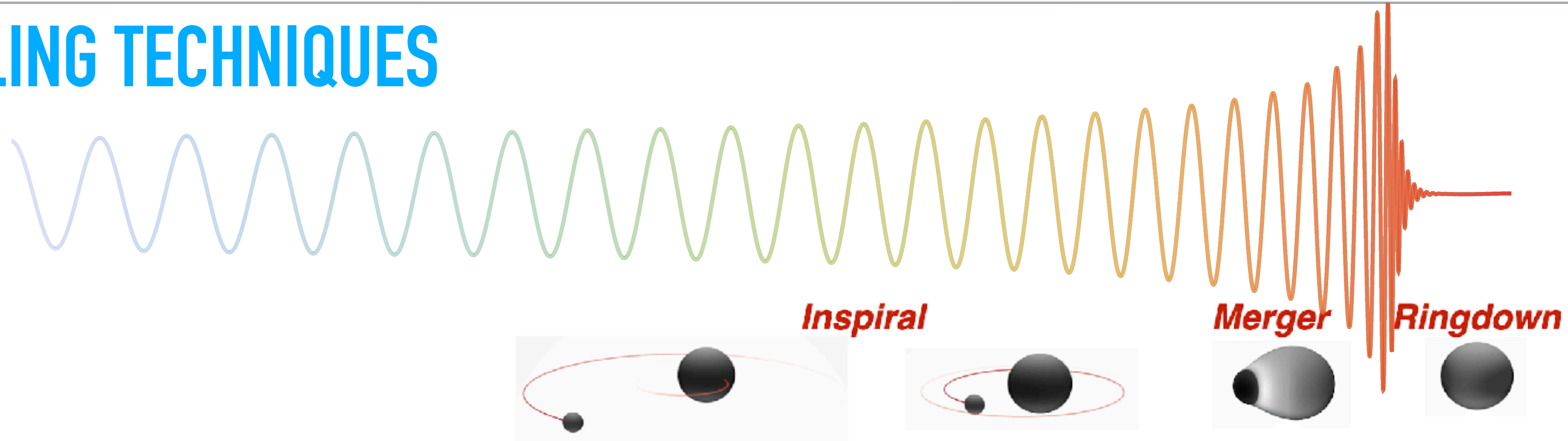
precessing spins



orbital eccentricity



MODELLING TECHNIQUES



ANALYTICAL RELATIVITY TOOLS

- ▶ **Post-Newtonian (PN) theory**
 - ▶ Weak fields & slow motion
- ▶ **Post-Minkowskian (PM) theory**
 - ▶ Weak fields, arbitrary velocities
- ▶ (uncalibrated) **effective-one-body** (EOB)
- ▶ **Effective field theory (EFT)**
- ▶ **Scattering amplitudes**
 - ▶ Hyperbolic motion
 - ▶ Map to the bound case
- ▶ **Gravitational self-force (GSF)**
 - ▶ Very unequal mass ratios
- ▶ (Classical) **Perturbation theory**
 - ▶ Ringdown

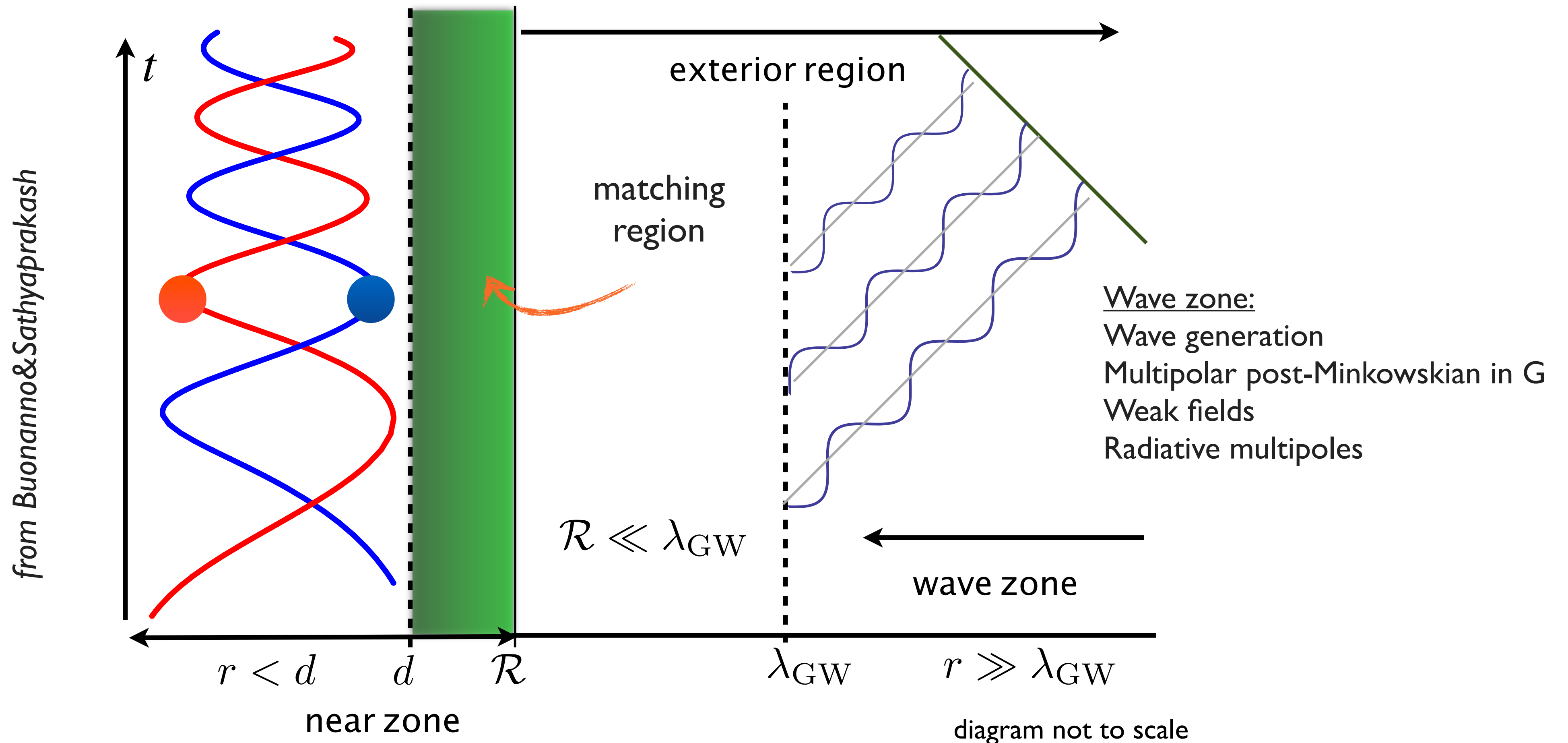


"Tutti Frutti"

MODELLING THE INSPIRAL

[See Blanchet's LRR review]

- ▶ Multi-length-scale problem



Near zone:
 Equations of motion
 Post-Newtonian
 Weak fields & slow motion
 Source multipoles

$$\frac{v^2}{c^2} \sim \frac{GM}{r} \ll 1$$

Wave zone:
 Wave generation
 Multipolar post-Minkowskian in G
 Weak fields
 Radiative multipoles



GRAVITATIONAL WAVEFORMS

- ▶ A gravitational-wave signal can be written as:

$$h(f) = \mathcal{A}(f) e^{i\varphi(f)}$$

Amplitude Phase

- ▶ The GW phase encodes the physics:

$$\varphi(v) = \left(\frac{v}{c}\right)^{-5} \left[\overset{0\text{PN}}{\varphi_0} + \overset{1\text{PN}}{\varphi_2 \left(\frac{v}{c}\right)^2} + \dots + \overset{2.5\text{PN}(\text{!})}{\varphi_{5l} \ln\left(\frac{v}{c}\right) \left(\frac{v}{c}\right)^5} + \dots + \overset{5\text{PN}}{\varphi_{10} \left(\frac{v}{c}\right)^{10}} + \dots \right]$$

$\mathcal{M} = \frac{(m_1 m_2)^{3/5}}{(m_1 + m_2)^{1/5}}$

$q = \frac{m_2}{m_1}$

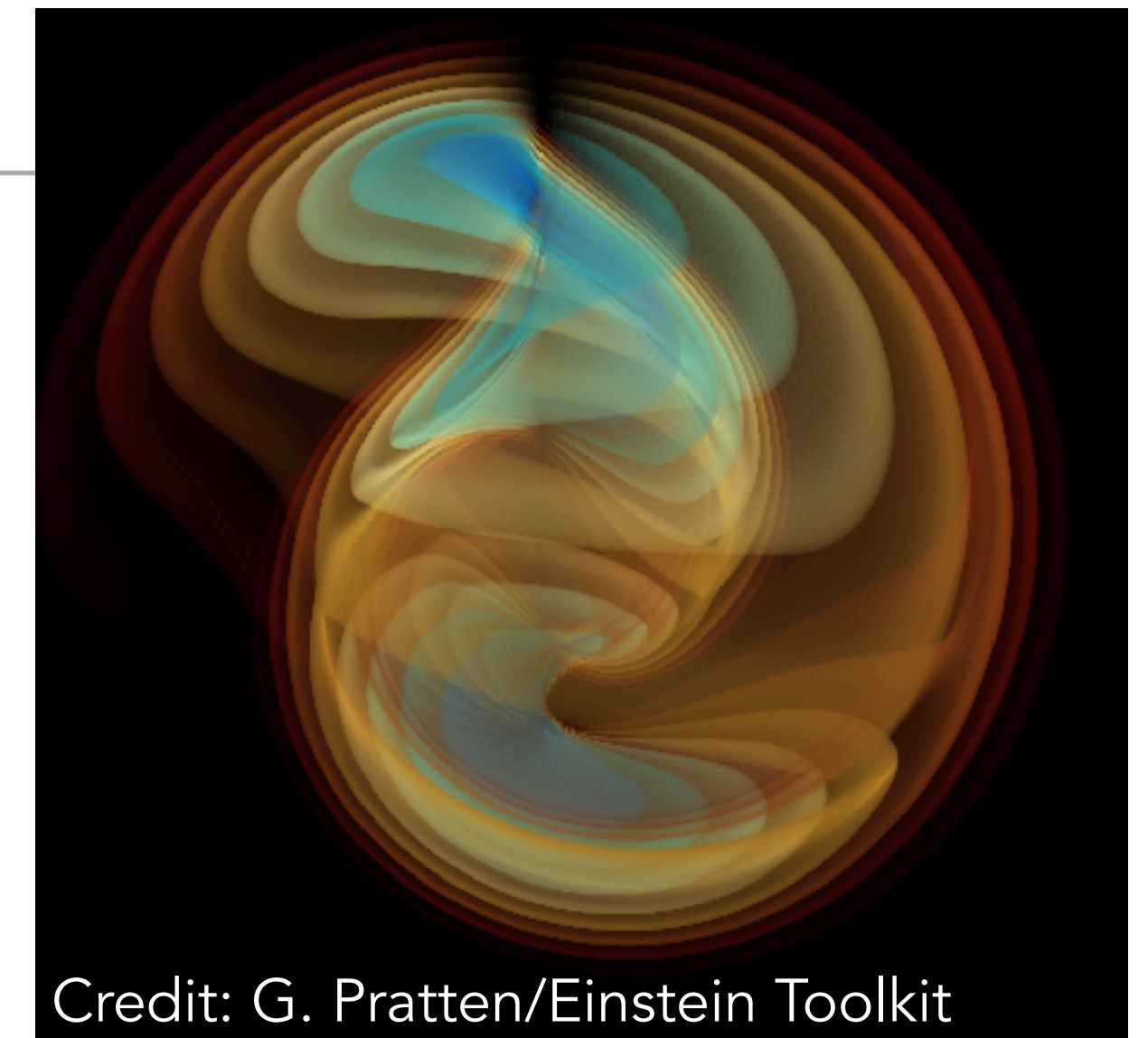
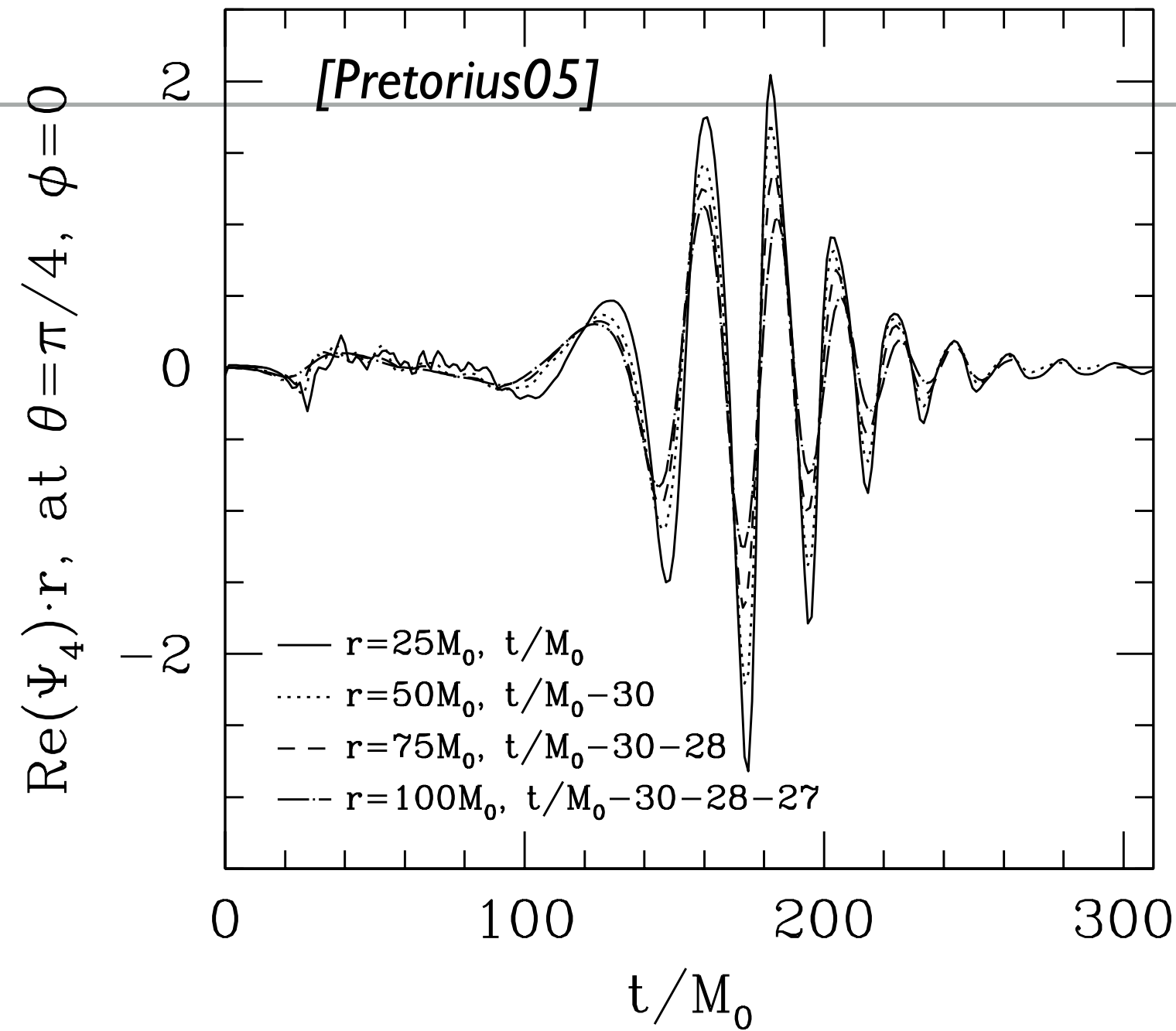
Tail terms ~ back reaction due to scattering

Tidal effects first enter here...

MODELLING TECHNIQUES

NUMERICAL RELATIVITY (NR)

- ▶ Only few analytic solutions to Einstein field equations known
- ▶ **No analytic solutions to the general-relativistic two-body problem**
- ▶ NR is a key ingredient to understanding GW observations!
- ▶ Breakthrough in 2005 [Pretorius, Baker+, Campanelli+]:
 - ▶ First stable binary evolutions
 - ▶ Extraction of the GW signal
 - ▶ Computationally expensive
 - ▶ Time consuming
- ▶ Many challenges remain!



Reformulate the Einstein field equations (EFE) as initial value problem (IVP)

Prove existence of a well-posed initial value problem

Numerically suitable reformulation of the EFE

"good" coordinates (gauge choices)

Initial data

Deal with singularities

"Find" the black hole horizons

Extract gravitational waves

